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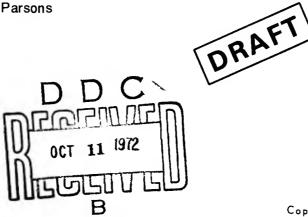
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**OCTOBER 1972** 

## **CARMONETTE IV** and CARMONETTE V

by Norman W. Parsons



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Research Analysis Corporation

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# CARMONETTE IV and CARMONETTE V

by

Norman W. Parsons



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#### FOREWORD

Letter DARD-ARG-S, 8 Aug 72 from the Office of the Chief of Research and Development, Department of the Army states in part:

"A gap exists in the documentation available to the Army concerning the CARMONETTE model. The latest complete documentation was the three volume RAC-R-28 that covers CARMONETTE III. These volumes were published in the period October 1967 through February 1968. Since that time, the model has been converted to the Control Data Corporation 6400 computer, and CARMONETTE IV and V have been developed. CARMONETTE IV and V were developed primarily for use in specific studies, and the documentation of these editions is contained only in those study reports. Since the reports are classified, and bulky, this is an undesirable situation for the Army analyst interested in the model only.

There exists within RAC, an unclassified Coordination Draft dated 11 November 1971 that covers the changes to CARMONETTE III as a result of the computer change and the development of CARMONETTE IV and V. The Army desires that RAC publish and distribute that Coordination Draft so that the Army will have access to the most recent CARMONETTE documentation in an unclassified form. Recognizing that the Coordination Draft may not conform to RAC standards for technical publication, there is no objection to publishing it as a draft.

Accordingly, you are authorized to publish and distribute document 'CARMONETTE IV and CARMONETTE V,' Coordination Draft, dated 11 November 1971."

This document is published in accordance with the above quoted letter.

DONDERO

Director

Gaming & Simulations Department

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#### INTRODUCTION

This document presents the changes that have been made in the CARMONETTE simulation since the publication of the CARMONETTE III documentation.

The details of the CARMONNTTE III small unit battle simulations are documented in RAC R-28 (Vol I, Oct 67, AD 822400L; Vol II, Feb 68, AD 827900; Vol III, Jan 68, AD 825000).

In the period since the publication of the CARMONETTE III documentation, material changes have been made in the logic and details of the program. The program has been rewritten to convert it from the IBM 7040 computer, described in the CARMONETTE III documents, to the CDC 6400 computer. CARMONETTE IV is the version of the simulation resulting from the changes made to incorporate the employment of night vision devices. These changes were described in the report, "The Use of CARMONETTE IV in Assessing the Effectiveness of Small Units Equipped with Night Vision Devices," Draft, Nov 69, AD 514519L. CARMONETTE V is the version of the simulation resulting from the changes made for the Equal Cost Firepower Study (ECF-1) (Draft client report, Sept 71, undistributed).

This document includes the sections of the CARMONETTE IV report and the ECF-I report which discuss the details of the changes made to the CARMONETTE simulation since the publication of the CARMONETTE III documents. Minor changes have been made for the sake of coherence of this document.

#### THE CARMONETTE SIMULATION

GENERAL

CARMONETTE is a fully computerized Monte Carlo mathematical simulation of small unit ground combat. It is a time-sequenced critical-event war game that simulates the activities of movement, target acquisition, communications, and weapon employment by infantrymen and various vehicles, including tanks, armored personnel carriers, and helicopters, and a wide variety of weapons. Resolution can be at the level of the individual soldier or vehicle, or at squad or platoon level. Up to a reinforced-battalion-size force can be represented on each side.

CARMONETTE plays on a terrain simulation of 3780 grid squares (60 by 63).\* The arrangement of the grid squares is fixed, but the grid size may range from 10 m to 250 m or larger depending on the size and type of units being simulated. Each grid square is described in terms of average elevation, available cover and concealment, crosscountry and road trafficability, and height of vegetation.

CARMONETTE runs from a predetermined scenario and each unit is required to have explicit orders for its actions. Certain contingency type orders are available under which the actions of a unit will depend on its knowledge of and the actions of enemy or other friendly units. Battles as long as 60 to 90 minutes can be simulated.

<sup>\*</sup>In CARMONETTE V. CARMONETTE IV was 36 by 63.

#### LOGIC CHANGES FOR CARMONETTE IV

#### General

In the development of CARMONETTE IV from CARMONETTE III several important changes and additions have been made in the logic of the simulation. A new type of unit, a Command, Control, and Surveillance Unit (CCSU), has been added. The previous Target Acquisition Routine has been separated into a Surveillance Routine and a Target Acquisition Routine. An entirely new routine, the Communications Routine has been added.

#### Command, Control, and Surveillance Units

The identification of the CCS units as being separate from the weapon units permits the play in the simulation of surveillance devices which are not weapon aiming devices. This type of device includes the hand-held thermal detector, the radars, and the night observation device. The CCS units conduct surveillance with their assigned devices; two different devices may be assigned to each unit, and when targets are detected, nearest square information is transferred to the weapon units subordinate to that CCS unit and also to its superior CCS unit by means of the Communication Routine.

A total of 27\* CCS units can be established for each side. These are in addition to the 36\* possible weapon units on each side. The limit of 63 total units is determined by the two digit octal mathematics that is used in the simulation. The CCS units are identified as units 37 through 63 even though less than 36 weapon units are played.

The CCS units are not assigned any weapons and thus do not participate in the exchange of fire. CCS units are not subject to detection and will be killed only when their last assigned subordinate unit is killed. A weapon unit must be identified as the "Buddy Unit" for each CCS unit. Separate movement orders are not prepared for the CCS units; instead each CCS unit accompanies his buddy and moves in accordance with

3

<sup>\*</sup>In CARMONETTE V these numbers were changed to 15 CCS units and 48 weapon units.

that unit's orders. If the first assigned buddy unit should be killed, the CCS unit transfers itself to the next listed subordinate unit. If the CCS unit is not in the actual chain of command, i.e., the forward observers and the radar teams, one of the weapon units must still be assigned as the buddy unit. Dummy subordinate units may also be assigned to provide for continuity of action by the CCS unit if the first buddy unit is killed. A weapon unit may serve as the buddy unit for more than one CCS unit in which case they would all be assumed to move together.

In the night vision games the capability of calling artillery fires, an assignable capability to any CARMONETTE unit, has been restricted to CCS units on each side. On the Blue side only the CCS units identified as forward observers can call artillery. On the Red side the platoon leaders have this ability.

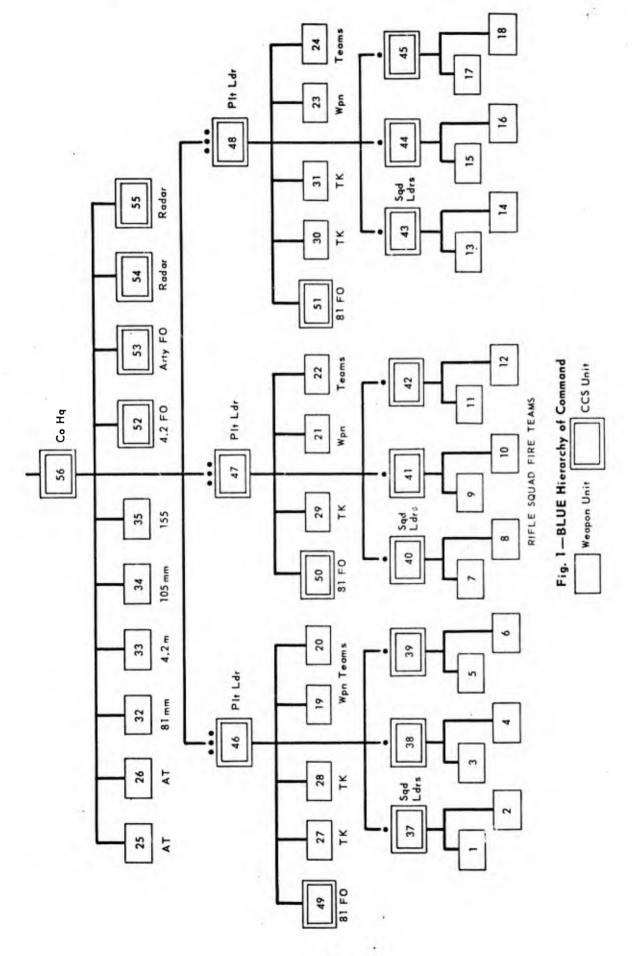
The CCS units do not enter the Target Acquisition Routine and the Position Disclosure Routine and thus are limited to acquiring detection, i.e., nearest square level of information.

The hierarchy of command established for the night vision games for the Blue side is shown in Fig. 1.

#### Surveillance Routine

The Surveillance Routine is the portion of the Battle Model in which target detections are determined. Figure 2 is a flow chart of the Surveillance Routine.

A surveillance cycle (also called scan time) is input for each sensor and this time determines the frequency at which a unit conducts surveillance with that sensor. In the night vision games this interval is 1 minute for all sensors except unaided eye which is 0.5 minute. When the surveillance clock for each sensor device becomes the lowest clock of the unit's list of ordered events, that unit's master clock is set for surveillance with that device. At the beginning of the game, the initial setting of all the surveillance clocks of all units is set to random times so that the units in the game will conduct surveillance at different times.



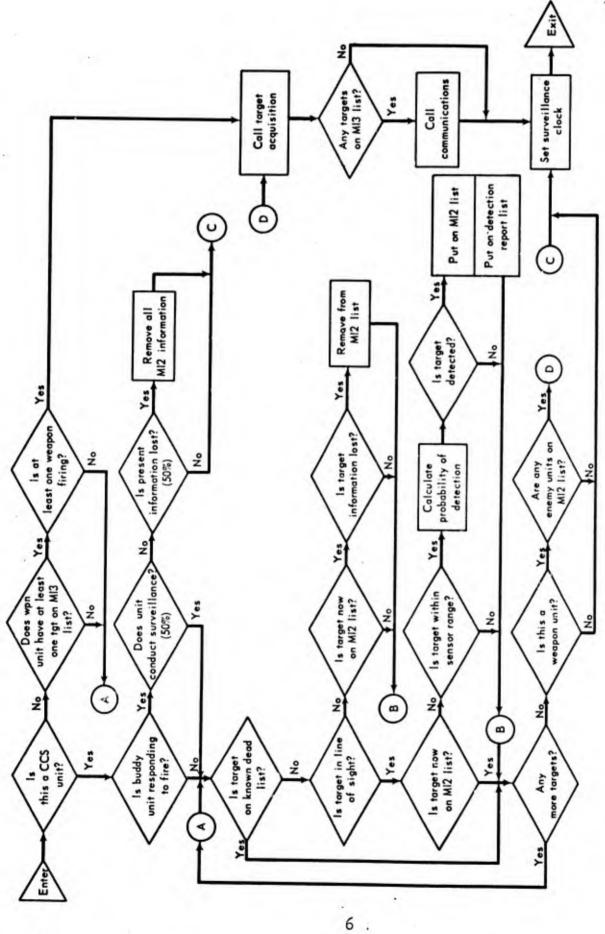


Fig. 2—Flow Chart—Surveillance Model

When a unit is conducting surveillance the computer processes each opposing unit for consideration of possible detection. If the target passes the following tests:

It is not on the known dead list

It is in line of sight

It is not already detected

It is within sensor range

a probability of detection is calculated as discussed in App A and a random number is drawn to determine whether or not a detection is made. (Note: as discussed in App A, a Computational Routine is not used for IR sensors (Class 3) and detections are determined for these sensors in the Target Acquisition Routine.)

If a weapon unit is already firing at a target when the weapon unit enters surveillance it does not conduct surveillance but goes directly to the Target Acquisition Routine where it randomly changes the information it already has.

A CCS unit that is in a grid square where enemy fire is of sufficient volume to neutralize the units there, has only a 0.5 probability of attempting surveillance. If surveillance is not attempted the unit has a 0.5 probability of losing any information it now has.

When all enemy units have been processed for a weapon unit, if any targets have been detected, the unit goes to the Target Acquisition Routine and randomly changes the information. Otherwise the unit surveillance clock is set for the next cycle as is done for CCS units.

#### Target Acquisition Routine

The Target Acquisition Routine is the portion of the Battle Model in which weapon units randomly change the information about detected targets. Figure 3 is a flow chart of the Target Acquisition Routine. A CCS unit that is assigned an IR sensor (Class 3) also uses the Target Acquisition Routine to determine target detections; however, higher states of information are not retained if the unit does acquire them.

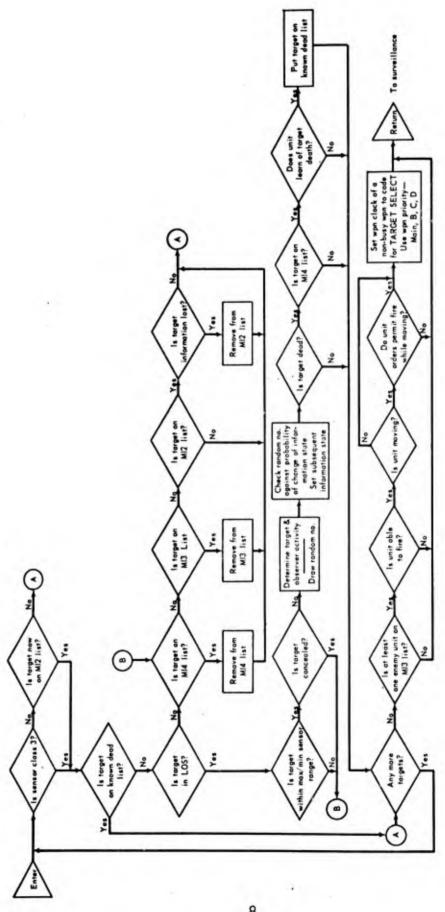


Fig. 3—Flow Chart—Target Acquisition Model

When a weapon unit enters the Target Acquisition Routine the computer again processes the complete list of enemy units; however, units that are not already detected (on the Ml2 list) are skipped. If the target unit passes the following tests:

It is not on the known dead list

It is in line of sight

It is within sensor range

It is not concealed

a random number is drawn and compared with the probabilities in the change of information matrix (discussed in App A) to determine the subsequent level of information.

If a target is dead, but not previously known to be dead, and accurate information (pinpoint) is acquired about it, there is a probability that the target death will be learned.

It is possible for a target to be on the detected (or a higher level) list when it is not in line of sight. This occurs when a previously detected target (or the detecting unit) moves so that line of sight no longer exists and may occur when a unit is given information through the Communication Model. When this situation exists the information will be degraded one state each surveillance cycle until only detection information is known, then there is a 0.5 probability that this information will be lost.

When the Target Acquisition Routine is completed for all enemy units, if a weapon unit has acquired at least erroneous pinpoint information (Ml3 list) on one target, and the unit is able to fire, the unit will go to the Target Select Routine and assign one of its weapon groups to fire at the target. The unit then returns to surveillance and if information has been acquired in target acquisition the unit goes to the Communications Routine to transmit this information.

#### Communications Routine

The Communications Routine permits all units to exchange target information. Figure 4 is a flow chart of the Communications Routine.

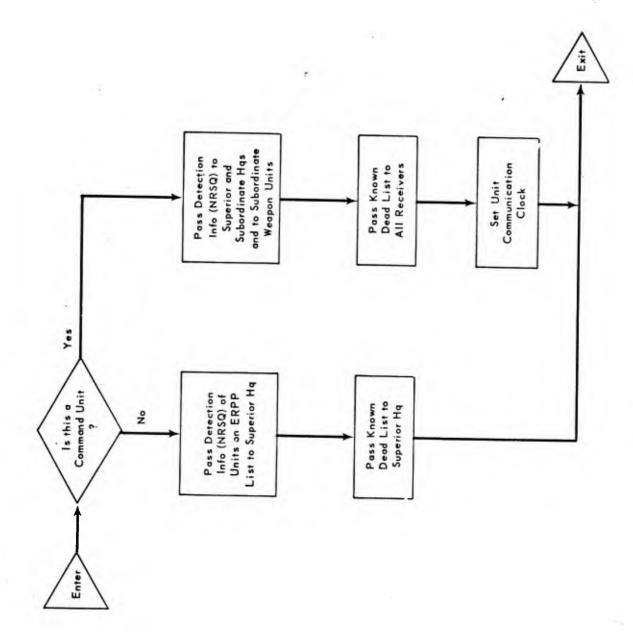


Fig. 4—Flow Chart—Communications Routine

When a weapon unit acquires information higher than detection (M13 or M14 lists) in the Target Acquisition Routine it transfers detection information on these targets and also the known dead information to its superior CCS unit. A communications cycle, currently 1 minute, is established for the CCS units. At the end of the communication cycle each CCS unit transfers to its immediate subordinate weapon and CCS units and to its superior CCS unit (See Fig. 1) whatever detection (nearest square) and known dead information it has.

#### CARMONETTE V

CARMONETTE V is an expansion and revision of the CARMONETTE  $III^1$  and CARMONETTE  $IV^2$  versions of the simulation. This document will discuss the changes that were made to produce CARMONETTE V. Readers who are not familiar with the earlier versions of CARMONETTE are referred to the appropriate documentation.

#### Map Size

The size of the map of the playing area has been expanded to 60 by 63 grids from the previous size of 36 by 63 grids.

#### Number of Units

The number of weapon units on each side that can be played has been increased from 36 to 48. The number of command and control units that can be played is reduced from 27 to 15 to keep the total number at 63, the limit of the two digit actual number space allocation. The first identified command unit must be number 49 regardless of the number of weapon units being played.

#### Remount Routine

Earlier versions of CARMONETTE included a Dismount Routine in which a mechanized infantry unit could be given orders to dismount from their carrier(s) and fight on foot. The carriers could then be given orders to move to a different location.

To permit the play of delaying tactics that was desired in the ECF runs, a Remount Routine for the APC transported infantry was included in the program. By using this routine the infantry can be placed on their initial defensive position and at an appropriate time in the game they will remount and move to a second (and third) position to continue the battle.

#### Helicopter Model

The helicopter model which had been available in the IBM 7040 version of CARMONETTE III was recreated and expanded. The helicopter model can simulate the actions of attack helicopters, reconnaissance helicopters and troop transport helicopters.

The Attack Helicopter Routine has been modeled to simulate the "pop-up" tactics currently (1971) regarded as the most desirable against a sophisticated enemy.

#### Vehicle Kills by Artillery

The Artillery Assessment Routine in earlier versions of CARMONETTE assessed the effects of artillery fires only against dismounted infantry. In CARMONETTE V the Artillery Routine has been expanded to include the assessment of the effect of DP/ICM munitions against vehicles.

#### Range of Engagement Summary

A new Postprocessor Routine has been created which extracts and assembles information from the battle history tape. This routine presents a summary of all engagements (firing actions), vehicles killed, and troops killed, by each type of weapon against each target class for each 100 m range bracket in the particular game concerned.

#### Details of Changes

These new routines for CARMONETTE V are discussed in more detail in Appendix B.

The revision of the input forms necessitated by the changes in CARMONETTE IV and CARMONETTE V is shown in Annex Bl.

#### Example of Inputs

As an example of the inputs for a CARMONETTE run a listing of the input cards for one of the father-son sets is shown in Annex B2.

#### Running Guide and Data Storage

The revised running guide and list of data storage allocations resulting from the changes in CARMONETTE V are shown in Annex B3.

#### Appendix A

## PROBABILITIES OF DETECTION AND PROBABILITIES OF CHANGE IN INFORMATION STATE

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### PROBABILITIES OF DETECTION AND PROBABILITIES OF CHANGE IN INFORMATION STATE

#### PREVIOUS CARMONETTE TECHNIQUES

In the CARMONETTE III simulation the determination of target detection and of subsequent higher quality of information is a Markov chain process. The probability of acquiring a higher quality of information is dependent on the level of information now known about the target. The various probabilities are dependent on the range to the target, the cover available in the target grid square, and on target and observer activity. The observer-target range is identified in four range brackets which are determined by three solid angle threshold values of the visual solid angle presented to the observer by the target.

The simulation uses four states of information about a target: State 1 is "no information;" State 2 is target location known to the "nearest grid square;" State 3 is identified as "erroneous pinpoint;" the observer believes he knows the correct target location but in fact does not, direct fire at the target is ineffective; State 4 is "pinpoint," the target location is accurately known.

#### CARMONETTE IV DETECTION ROUTINES

In order to consider more explicitly the characteristics of the surveillance devices being examined, specific detection routines were developed\* for the ee of the four classes of sensors being played in the

<sup>\*</sup>The detection routines were developed from information furnished by Dr. Walter Lawsen of the Night Vision Laboratory, Ft. Belvoir, Va., who also provided the input data required.

CARMONETTE IV simulation. In these routines the probability of detection of the target is separately computed for each target surveyed during each surveillance cycle. Appropriate factors such as target reflectance, background reflectance of the grid square occupied by the target, target dimensions, target speed (for radar), and device characteristics are inputs to the computational routines. Computational detection routines are provided for the visual, image intensifier, and radar classes of sensors. Such a detection routine is not provided for thermal sensors because of the greater complexity of the computations and the immediate unavailability of input data and device characteristics. Detection by thermal devices relies on the earlier concept of predetermined inputs for probability of detection.

The acquisition of a higher level of target information is based on the original CARMONETTE concept of a Target Information Transition Matrix for all devices.

#### IMAGE INTENSIFIER ROUTINE

The input and computational variables and the computation techniques for the image intensifier routine are shown in Table Al.

In the execution of the computations, those calculations which are based on the input values (night sky brightness and various constants) are performed in the preprocessor program. Figure Al is a flow chart of these computations. The probability of detection calculations which use the target and background reflectance values are performed in the battle model program. Figure A2 is a flow chart of these computations.

Table Al

IMAGE INTENSIFIER MODEL CALCULATIONS

Symbol	Definition	Typical value or computation
σ <sub>s</sub>	Scattering cross section	7.05 x 10 <sup>-5</sup>
σ <sub>a</sub>	Absorption cross section	1.08 x 10 <sup>-3</sup>
C <sub>G</sub>	Constant	0.75
<sup>1</sup> 2	Constant	0.256
5	Time constant, seconds	0.1
	System "f" number	_
o	Objective lens focal length, mm	
c	Electron charge, coulombs	1.6 x 10 <sup>-19</sup>
	Observer - target range (m)	(calculated)
	Device transmission	0.92
( <sub>Y</sub> )	Transfer function	Fig. A3
TF	Modulation transfer function	_
TC	Modulation transfer constant	$MTF = \int T(\gamma)d\gamma$ $MTC = 1000$
r	Resolution length	$MTC = \frac{1000}{MTF \cdot F_{O}}$ $\sigma_{r} = \frac{1}{2 \sqrt{2 \pi MTF}}$
(λ)	Night sky spectral radiance	2 √2 π MTF
	Moonlight	$B(\lambda) = 10^{(237\lambda - 7.87)} \times 10^{-}$
	Part moon	$B(\lambda) = 10^{(+.480\lambda - 8.76)}$
	Starlight	$B(\lambda) = 10^{(+.480\lambda - 8.76)} \times 10^{(+.145\lambda - 9.95)} \times 10^{(+.145\lambda - 9.95)}$
(λ)	Photocathode sensitivity	Fig. Al4
3	Computational variable	$P_{2} = \frac{1}{e_{c}} \int B(\lambda)Q(\lambda)d\lambda$

Table Al (continued)

Symbol	Definition	Typical value or computation
K	Computational variable	$K_1 = \frac{t \tau \pi}{\mu f^2}$
K	Computational variable	$K_{\mathbf{z}} = 4 \pi \sigma_{\mathbf{r}}^{\mathbf{z}}$
$R_{B}(\lambda)$	Background reflectance	Table A2
$R_{\mathrm{T}}(\lambda)$	Target reflectance	Table A3
M <sub>1</sub>	Image intensifier background reflectance	$M_1 = \frac{1}{e_c} \int R_B(\lambda) B(\lambda) Q(\lambda) d\lambda$
M <sup>S</sup>	Image intensifier target reflectance	$M_{z} = \frac{1}{e_{c}} \int R_{T}(\lambda)B(\lambda)Q(\lambda)d\lambda$
T	Transmittance	$T = e^{-(\sigma_S + \sigma_a)R}$
K <sub>3</sub>	Computational variable	$K_3 = 1 - e^{-\sigma_S R}$
co	Intrinsic contrast	$C_{o} = \frac{ M_{1} - M_{1} }{M_{1}}$
С	Received contrast	$C = \frac{C_{O}}{1 + \frac{K_{3} P_{2}}{C_{G} \cdot T \cdot M_{1}}}$
$N_{\rm B}$	Computational variable	$N_B = K_1  M_1 \cdot T \cdot C_G + K_3 \cdot P_2$
N	Noise strength	$N = \frac{K^{S}}{N^{B}}$
S	Signal strength	$S = C \cdot N_B$
SN	Signal to noise ratio	<u>S</u>
$N_{ t eff}$	Computational variable	0
	for SN < 5.0	$N_{eff} = SN \frac{2}{5} MTF$
	for SN ≥ 5.0	$N_{eff} = 2MTF$
$N_{\mathbf{f}}$	Computational variable	$N_{f} = 1000 \frac{MD}{R} N_{eff}$
$P_{D}$	Probability of detection	$P_{D} = 1 - e^{-(N_{2} \cdot N_{f}^{2})}$

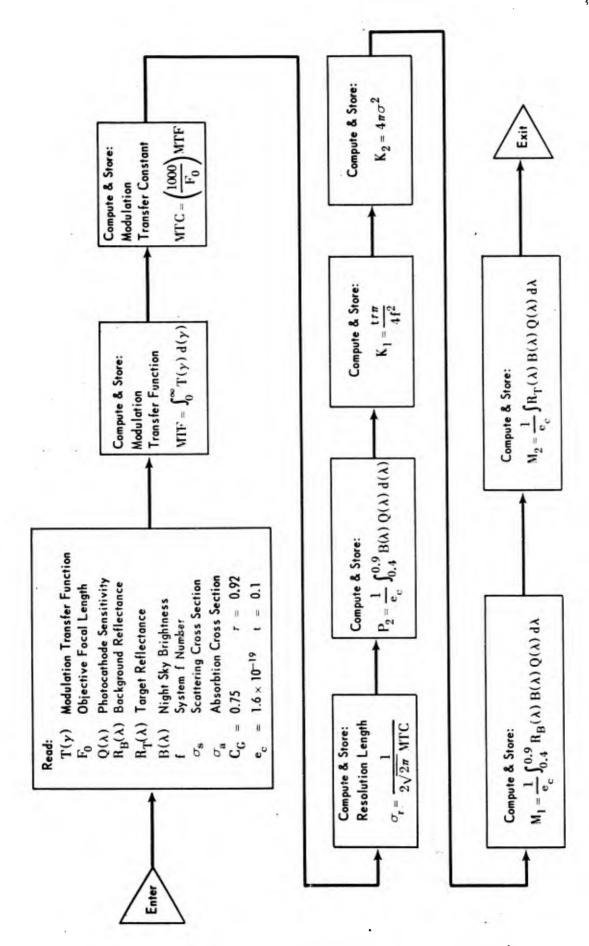


Fig. A1—Flow Chart—Preprocessor Computations—Image Intensifier Detection Model

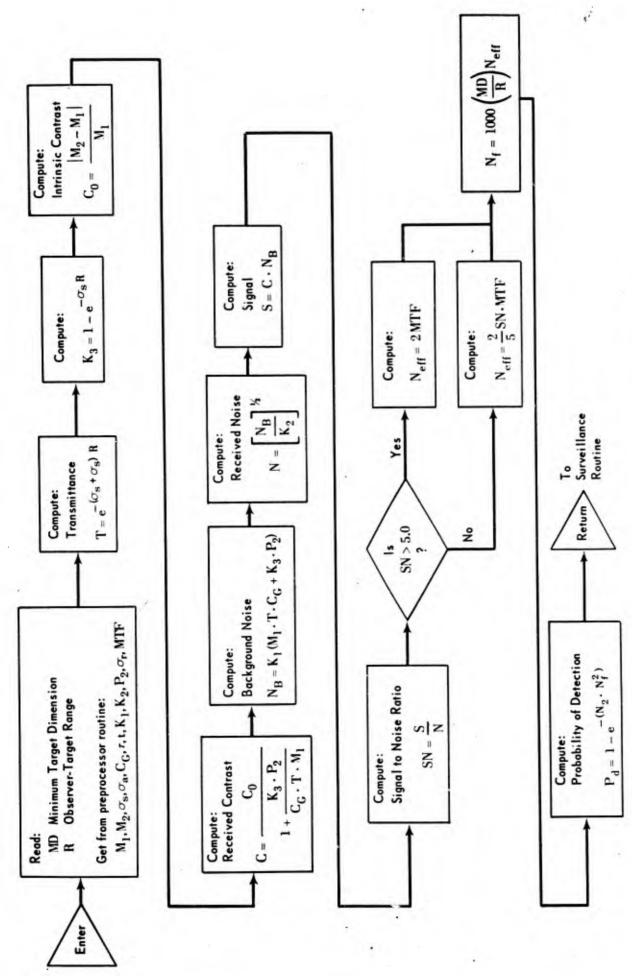


Fig. A2—Flow Chart—Probability of Detection—Image Intensifier

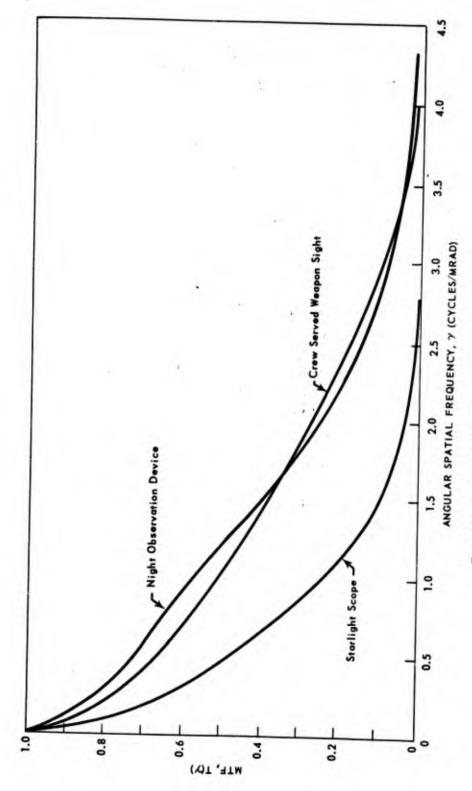


Fig. A3—System Modulation Transfer Function (MTF)

Note: The Modulation Transfer Function is a characteristic of an imaging system which expresses the loss in modulation in the output signal reference the input signal in relation to the object spatial frequency  $\gamma$  in cycles per milliradians.

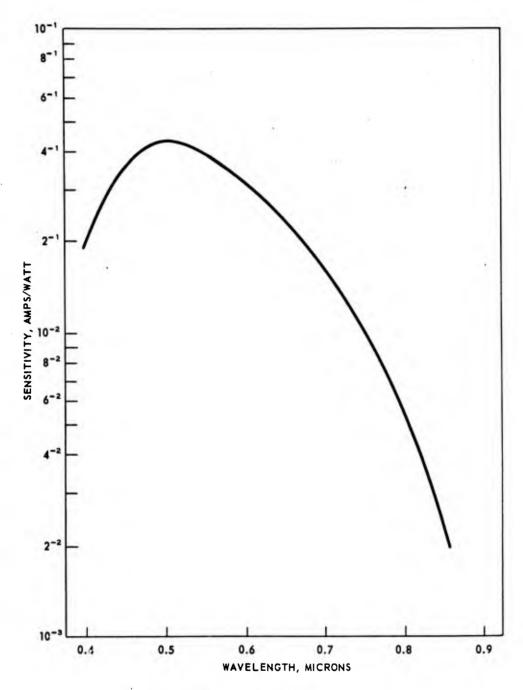


Fig. A4—S-20 Photocathode Sensitivity,  $\mathbf{Q}(\lambda)$ 

Note: The S-20 is the photocathode tube used in the first generation of passive night vision devices.

Table A2
BACKGROUND REFLECTANCE

Wave	Type background				
length (Microns)	Trees, grass (Summer)	Coniferous (Summer)	Trees, grass (Autumn)	Leaves	Elephant grass
0.4	0.04	0.04	0.05	0.03	0.05
0.5	0.07	0.04	0.08	0.05	0.05
0.6	0.12	0.08	0.20	0.12	0.05
0.7	0.18	0.14	0.32	0.18	0.12
0.8	0.52	0.28	0.54	0.20	0.38
0.9	0.56	0.32	0.56	0.19	0.41

Table A3
TARGET REFLECTANCE

Wave	Type target			
length (Microns)	Fatigues	Tank	Viet hat	Black shirt
0.4	0.05	0.10	0.18	0.05
0.5	0.05	0.11	0.25	0.05
0.6	0.08	0.13	0.30	0.05
0.7	0.12	0.13	0.38	0.08
0.8	0.25	0.13	0.52	0.15
0.9	0.32	0.13	0.55	0.16

#### VISUAL DETECTION ROUTINE

The input and computational variables and the computation techniques for the visual detection routine are shown in Table A4.

Figure A5 is a flow chart of the computations performed in the preprocessor program and Fig. A6 is a flow chart of the computations in the battle model program.

Table A4
VISUAL DETECTION MODEL CALCULATIONS

Symbol	Definition	Typical values or computations
$\sigma_{_{\! S}}$	Scattering cross section	7.05 × 10 <sup>-5</sup>
$\sigma_{\!a}$	Absorption cross section	1.08 × 10 <sup>-3</sup>
$^{\mathrm{C}}_{\mathbf{G}}$	Constant	0•75
α	Constant	0.5 unaided eye 33.0 7 x 50 binoculars
MD	Minimum dimension of target (meters)	0.1 - 7.9
MAG	Magnification	1.0 unaided eye 7.0 7 x 50 binoculars
N <sub>1</sub>	Constant	1.5 unaided eye 0.01 7 x 50 binoculars
R	Observer target range	(calculated)
Β(λ)	Night sky spectral radiance Moonlight Part moon Starlight	$B(\lambda) = 10^{(237\lambda -7.87)} \times 1$ $B(\lambda) = 10^{(+.480\lambda -8.76)} \times 1$ $B(\lambda) = 10^{(+1.45\lambda -9.95)} \times 1$
$R_{B}(\lambda)$	Background reflectance	Table A2
$R_{T}(\lambda)$	Target reflectance	Table A3

Table A4 (continued)

Symbol	Definition	Typical values or computations
<b>K(λ)</b>	Relative sensitivity of the eye	e Table A5
β	Angular size of a minimal visil target (Blackwell)	ble Figure A7
M <sub>.</sub> a	Visual background reflectance	$M_3 = \int_{\dot{R}_B} (\lambda) B(\lambda) K(\lambda) d\lambda$
M <sub>4</sub>	Visual target reflectance	$M_4 = \int R_T(\lambda)B(\lambda)K(\lambda)d\lambda$
P <sub>1</sub>	Integral of night sky brightness	$P_1 = \int B(\lambda)K(\lambda)d\lambda$
IL	Light level	LL = $\pi \alpha (685)(9.3 \times 10^4)P_1$
T	Transmittance	$T = e^{-(\sigma_s + \sigma_a)R}$
К <sub>з</sub>	Computational variable	$K_3 = 1 - e^{-\sigma_S R}$
co	Intrinsic contrast	$C_{O} = \frac{ M_{4} - M_{3} }{M_{3}}$
C	Perceived contrast	$C = \frac{C_{O}}{1 + \frac{K_{3} \cdot P_{1}}{C_{G} \cdot T \cdot M_{3}}}$
$^{ m N}{ m f}$	Computational variable	$N_{f} = \frac{MD \cdot MAG}{R} $ (57)(60) $\frac{1}{8}$
$P_{\overline{D}}$	Probability of detection	$P_D = 1 - e^{(-N_1 \cdot N_f^2)}$

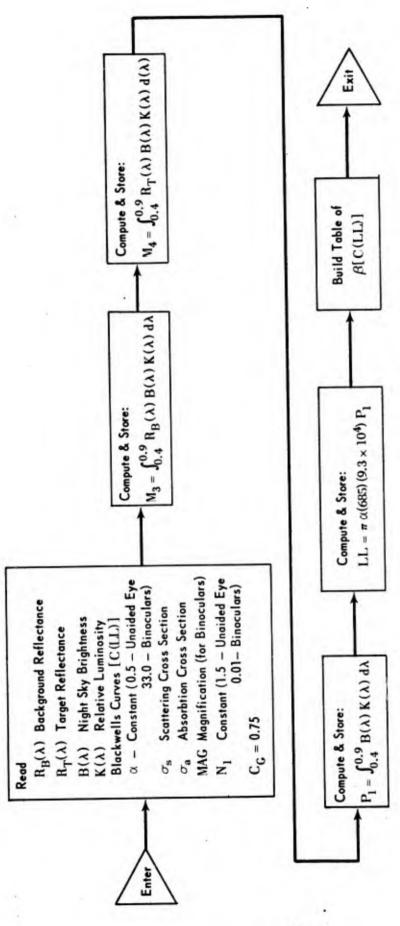


Fig. A5—Flow Chart—Preprocessor Computations—Visual Detection Model

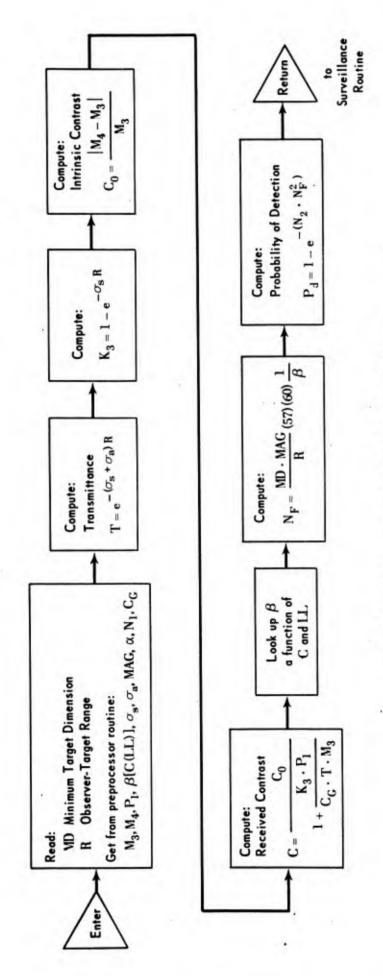


Fig. A6-Flow Chart-Probability of Detection-Visual

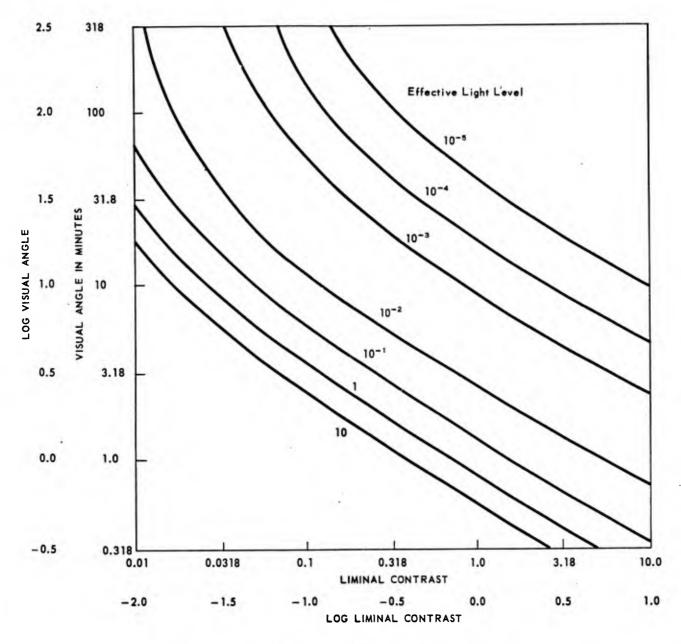


Fig. A7—Blackwell's Curves

Note: These curves show the angle subtended by a barely detectable target in relation to the target-background contrast and light level.

Table A5
RELATIVE SENSITIVITY OF THE EYE

Wave length (Microns)	к <sub>λ</sub>
0.4	4.37 x 10 <sup>-3</sup>
0.5	2.69 x 10 <sup>-1</sup>
0.6	$7.47 \times 10^{-1}$
0.7	3.55 x 10 <sup>-3</sup>
0.8	3.89 x 10 <sup>-6</sup>
0.9	1.70 x 10 <sup>-8</sup>

#### USE OF SENSOR CLASS IDENTIFIERS

In the CARMONETTE IV games the visual sensors, unaided eye and binoculars, were identified as Sensor Class 1. The image intensifier sensors were Sensor Class 2. The radars were Sensor Class 4. The Surveillance Routine is written so that these sensor classes are routed to the appropriate detection routines and then returned to the Surveillance Routine.

The other available sensor classes, i.e., 3, 5, and 6, are routed directly to the Target Acquisition Routine for determination of targets detected as well as the higher levels of information in accordance with the CARMONETTE III logic of the "Change of Information State Matrix."

There is no particular significance to these classes except that they provide for the possibility of inputting different values of detection probabilities.

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# CHANGES FOR THE CARMONETTE PROGRAM

#### GENERAL

The changes in the program required by the expansion of the number of units from 36 to 48 and the expansion of the map size from 36 by 63 grids to 60 by 63 grids did not require any changes in program logic. The necessary changes to the input forms are shown in Annex Bl.

The revised data storage words required by all of the program changes are shown in Annex B2.

### REMOUNT ROUTINE

In using the remount order the passenger unit must be mounted in the carrier unit at the beginning of the game. If the starting location of the passenger unit is to be the initial position for dismounted action, the first order to both the passenger unit and carrier unit must be "DISMOUNT." The carrier unit orders can then cause it to move to a rearward covered position. When the remount action is to occur the orders to each unit must cause them to move into a common grid square and then give each of them the order, "REMOUNT." If either the passenger unit or the carrier unit is killed while they are separated, the surviving unit will go to the ordered remounting square, find out that his partner is dead, drop to his next order and proceed on his mission. If the surviving unit was the passenger the movement in implementing the next order will be at the dismounted rate.

In the ECF games the TOW squads were given "out of ammunition" contingency orders which caused them to go to a covered position (escape point) when their 10 TOW missiles were expended. In at least one of the ECF delay games it was found that a TOW squad ran out of ammunition at the forward position and proceeded to move to the escape point prior to the time that it was to remount. The carrier for the squad, in attempting to carry out its portion of the remount order, moved to the ordered remount point at the proper time and waited there for the rest of the game. This anomaly in the program has been corrected so that the carrier unit will also go to the escape point when its passenger unit does.

#### HELICOPTER MODEL .

As previously stated, the helicopter model can simulate the actions of attack helicopters, reconnaissance helicopters and troop transport helicopters. The different types are identified by air mobility class Nrs 5, 6, and 7 (Form 18 and 19, Vol II, R-28) as follows:

Mobility class	Type helicopter
5	Attack
6	Reconnaissance
7	Transport

'All types of helicopters are also identified as fire response Class 5 on Form 7.

Helicopter units can be single or multiple element units just as any other CARMONETTE units.

Helicopter units can be given any type of order that is available in the CARMONETTE repertoire of orders except that an altitude index (from Form 20) must be included in the helicopter movement orders.

Several new orders for the Attack Helicopter Routine were also necessary.

The Attack Helicopter Routine is based on a Call Helicopter Routine similar in concept to the former Call Artillery Routine in CARMONETTE IV. Any command, control, and surveillance unit (CCSU) can be given the authority to Call Helo by an "X" in the appropriate column

on Form 36. This form has also been expanded to provide a set of target priorities against which the command unit will call helicopters or artillery.

Three new orders were created for the Helicopter Routine. These orders are:

Narrative order	Coded form
Change altitude to get line of sight to target	CHAL LOS
Change altitude to treetop	CHAL TRTP
Change altitude to land	CHAL LAND

In implementation of the Attack Helicopter Routine a sample set of possible orders to a helicopter unit is shown in Fig. Bl.

The STAY 5000 order puts the helicopter in an on-call status. When a command unit with authority to call helicopters identifies a target that is on his target priority list to at least the erroneous pinpoint level of information a non-busy helicopter subordinate to that command unit is called. The target number and location of the target is given to the helicopter (to the nearest square level of intelligence). The helicopter moves to the coordinates given in the move order. (This location is selected by the order/scenario writer based on the tactical situation being simulated.) When the helicopter reaches the specified "pop-up" location the computer determines the present location of the specified target and checks to see if line of sight exists from the pop-up point to the present target location at the maximum permitted altitude. In making this LOS check for the helicopter, when LOS is determined to exist, the computer also turns on the bit representing the helicopter in the enemy unit(s) LOS word. If the answer is "yes" the helicopter raises vertically to the minimum altitude required to achieve line of sight.

On reaching line-of-sight altitude the helicopter performs surveillance and target acquisition immediately without regard to the previously established surveillance time cycle. Surveillance will be performed again at current time plus surveillance cycle if the "stay interval" for

# ATTACK HELICOPTER ORDERS

	value can be any value larger than 1.0 minutes).
2.	STAY until TIME 500.0 (Helo is waiting to be called)(Command unit calls helo to Atk Tgt Type at specified square)
3.	Move no Stopping RATEto Square, Altitude
4.	Change Altitude to get LOS (Maximum altitude is listed in Form 18
5.	Stay Interval X.XX or FIRE 1 KIND 4 PRIORITY 1  (Helicopter performs Surveillance/Tgt Acq and fires at appropriate detected targets)
6.	Change Altitude to Treetop
7.	Stay Interval X.XX  (Repeat #4 - #7 as desired)(If fired at in sufficient volume to cause response skip to next move order)
15.	Move No Stopping RATE to Square, Altitude
16.	Change Altitude to LAND
17.	Stay Interval X.XX
19.	SKIP BACK 17 Unconditionally  (The successive "pop-ups" can be at different locations by inserting a Move Order ofter #6)

Fig. Bl - Sample Set of Helicopter Orders

the helicopter permits and if the helicopter has not aborted the action because of enemy fire. Each enemy unit in line of sight is processed for detection. If targets are detected the helicopter then selects a target based on the target priority list for his weapon. The target selected may or may not be the same target against which he was called. If no targets are detected to at least the erroneous pinpoint level, the helicopter unit will remain in that position for the interval specified in the order and then drop to the next order.

Any enemy unit that is in line of sight and that conducts surveillance and detects the helicopter while the helicopter is exposed may
fire at the helicopter if it is on the target priority list for any of
its weapons. The surveillance cycle for the enemy AD units should be
related to the "stay interval" of the helicopter so that the enemy units
will have an opportunity to execute a surveillance/target acquisition
cycle while the helicopter is exposed. It was also found to be necessary
to identify the enemy AD weapons as "guided missiles" (on Form 1) to
prevent the assessment of impact after the helicopter had dropped out of
LOS but before the computer performed the next LOS check.

After firing the specified number of rounds or waiting the specified time, the helicopter will drop to the next order.

In the Air Movement Routine the line-of-sight calculation, normally conducted at each boundary crossing for ground units, is conducted for air units only at the destination of each movement order. This change was made to reduce the number of repetitive computer calculations and thus hold down computer running time.

A reconnaissance helicopter unit can be given "fly-by" orders and if made the "buddy unit" of a command unit, the computer will simulate the calling of attack helicopters against targets from an airborne command post.

#### ARTILLERY ASSESSMENT AGAINST VEHICLES

The input form used to enter the kill probability of artillery and mortar against infantry (Form 14) has been revised to include a kill

probability against vehicles. An example of the revised form is shown in Annex Bl. It should be noted that this kill probability is entered as a four-digit decimal fraction. The type vehicle target is identified by "target class number." If any type of weapon or type of ammunition is not effective against a particular type vehicle, no entry is made at that point.

In determining the numerical value of these entries the calculation of the number of submissiles impacting in each grid square must first be done. Then the kill probability is:

 $P_{k} = \frac{\text{vulnerable area of vehicle}}{\text{area of grid square}} X Nr of submissiles$ 

X probability of kill given a hit.

#### RANGE OF ENGAGEMENT SUMMARY

An example of the printout from the range summary is shown in Figs. B2 and B3.

Instructions for producing this summary from the battle history tape are given in the Running Guide in Annex B3.

#### NEW AND REVISED ORDER FORMATS

In CARMONETTE III the total number of possible orders was limited to 250. In CARMONETTE IV the possible number of orders was increased to 500 and in the revisions for CARMONETTE V the possible number of orders was increased to 999. This change does not require any change in the technique of preparing orders.

The new remount order has the coded format for: REMØ

The altitude index for helicopter movement orders is entered as qualifier 5. The coded format of a helicopter movement order is:

NSTP RATE 7 SQRE XXYY KIND 6 PRØR 1 ALTD 2

BL UE N	WE AP ON	N0.	6	9 (105-mm Tank Gun)	5-mm Tank Gun)	는 상 연	n)								
α ·	RED TA	TARGET	CLASS	ASSES							8				
		ENG	RDS	V (Red	Tan	K) ENG RDS		<b>&gt;</b>	(Red APC)	ENG.	14	VEH A	npack	Manpack SAGGER)	
1001	1	0	0	0	0	1					0	0	0		
1501	2000	15	15	-	8	16	16	0	0	m	m	0	0		
2001	2500	19		0	0	8	8	0	0	0	0	0	0		
2501	3000	13	i	0	0	0	0	0	0	0	0	0			
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				TR	EATH	ENT	9	TREATMENT NO. 4202		PLI	REPLICATION NO.	NO	.0	· m	03/18/72
BLUE WE	WE AP ON	. ON	16 (	(DRAGOIN	(N										
2	RED TA	TARGET CLA	SLASS	ISSES											
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Fig. B2—Range of Engagement Printout, Each Replication

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Fig. B3—Example of Form 32, New Order Form

This qualifier is not entered on movement orders for ground units since the computer will read the blank as zero and the ground unit will move at zero altitude.

The change altitude orders for the Attack Helicopter Routine are:

	Narrative	2	•	Code	ed.
Change	altitude	to	get LOS	CHAL	LØS
Change	altitude	to	treetop	CHAL	TRTP
Change	altitude	to	land	CHAL	LAND

Figure B3 shows the new order forms as entered on a copy of the CARMONETTE Form 32, Orders.

#### Annex Bl

## INPUT FORMS

#### GENERAL

In the extension of CARMONETTE III to CARMONETTE IV, it was necessary to revise certain of the input data forms and to develop several new forms for the inputs concerning the command, control, and surveillance units and the various sensors now included in the simulation. Additional changes were required for CARMONETTE V. This annex presents the new and revised forms for both CARMONETTE IV and CARMONETTE V. For information concerning the other forms used for CARMONETTE inputs the reader is referred to Vol II of the CARMONETTE III documentation.

# FORM 3 - ORDER OF BATTLE

The only change in this form is the expansion of the form to provide for entries for 48 units. Figures B4 and B5 show examples of this form.

# FORM 4 - UNIT DESCRIPTION

Form 4 - Unit Description (Blue and Red), has been revised and expanded so that sensor class and sensor height can be entered. Form 4 is used for the weapon units of each side.

On the first line of Form 4 - Blue, Card No. 495, the total number of Blue and Red units being played is entered. The number of weapon units is entered in columns 2 to 5 and the number of CCS units is entered in columns 12 to 15. The superior headquarters (CCS unit) of the weapon unit is entered in columns 21 and 22. A superior headquarters identification

must be entered for each unit listed. The superior headquarters identification numbers must start with 49 regardless of the number of weapon units and cannot be larger than 63. For CARMONETTE V these forms were expanded to provide for 48 weapon units. Figures B6 and B7 show examples of Form 4 — Blue and Form 4 — Red.

ORDER OF BATTLE CARMONETTE V FORM 3-BLUE

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1 2 3	8 6 3	11 01 10 11		16 17 18	19 30	11 22 23 2	4 25 26 27	38	30 31 32 3	32 33 34 35 36 37 38 39		0 41 42	45 46	40 41 42 43 44 45 46 47 48 49 50 51	51 52 53	52 55	6 57 5	54 55 56 57 58 59 60 61 62 63 64 65 66 67 68 69 70 71 72	2 63 64	65 66 6.	99 49	17 07	27 27 24 75	73 74 75 76 77 78 79 80
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8 0 15	-	=	=	-		=	-	-	-	-	-	-	-	-	-	-	-	1111		-			UINITIS	14   2   7
B 0 16	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-	-		-				UINIT12	2  4 2 8
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0.4.0		-		-		-	-	-	-	-		-	-	-	-	-	-		-	-	_		UINITIZ	12 1417 10

 $TC \sim X$ , if unit is primenly a troop carrier? The next unit must refer to the dismounted troops. UTM  $\sim X$ , if unit unable to move? UTM  $\sim X$ , if unit unable to fire?

 $D\sim X$ , if troops dismount when hit?  $CA\sim X$ , if unit able to call artillery? HF  $\sim X$ , if unit holds fire until white eye range?

Fig. B4 - Form 3-Blue Order of Battle

FORM 3—RED ORDER OF BATTLE CARMONETTE V

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	-	-	-	-	-	=	-	-	-	-	-	-	-	-	-	-	-		1111	-			UINITIZ	12 14 17 11
R 0.12	1	-	-		-	-		-		-	-		-	-	-	-	-	-	1111	-			UINITIS	2 1417 12
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210 8	-		-	-	-	-	-	-	-	F	-	-	-	-	-	-	-	-		-			UINITIZ	2 1417 15
910 8	-			-	-	-	-	-			-	-	-	-	-	-		3	1111	-			UINITIZ	12 14 7 16
0 0 17	-			1	-	-	1	-	-	H	-	-	-	-	-	-	-	7	1111	-			UINITIZ	14 17 17
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R 315	-	=	-	-	-	-	_		H	H	7	-	-	-	-	-	-	-	1111	-			UINITIZ	2  4 8 4
R 316	-	-		-	-	=	=	-	-	A		7	-	-	-	-	-	-	111	-			UINITIZ	12 141815
R 317	-	=		-	-	=	=	7	-	7	1		1	-	-	-	-	-	1111	-			UNITIZ	12  4 8 6
318	-	-	-	-	-	-	-	-	-	7	=			1	-	-	-	-		-			UINITIZ	12 141817
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TC ~ X, if unit is primenly a troop UTM ~ X, if unit unable to move? UTF ~ X, if unit unable to fire?

CA X, if unit able to call artillery?

HF - X, if unit holds fire until white eye range?

Fig. B5 - Form 3-Red Order of Battle

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Fig. B6 - Example of Form 4-Blue

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- Example of Form 4- Red Fig. B7

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# FORM 14 - PROBABILITY OF KILLING INFANTRY

This form, which is used to input the kill probabilities of fragmenting munitions, is expanded to provide for entries for the kill probabilities against vehicles for weapons 1 through 8. In CARMONETTE weapons 1 through 8 are direct fire weapons. Provision is made for entries for two types of ammunition for each weapon. Note that the entries for  $P_k$  against vehicles is a four-digit decimal fraction compared to the two-digit entry for the  $P_k$  against dismounted infantry. Figure B8 shows an example of this form.

WIPINIS 161816 W.P.IN.8 161819 WIP IN 18 161910 W.P.N.8 161912 \* P | M | 8 | 16 | 9 | 6 W.P.IN | 8 | 16 | 8 | 5 W|P|N|8 |6|8|7 W P N 8 16 8 8 WIPINIS 161911 16 | 9 | 3 WIPINIS 161914 WIP IN 18 16 19 15 WIPINIS 161917 SIPINIS 161918 WIPINIS 171111 WIPINIS 171112 171113 WIPINIS 171114 WIPINIS 17116 WIPINIS 171210 171115 WIPINIS 171118 WIPINIS 17119 WIPINIS 171117 WIP IN 18 WIPINIS W P N 8 9 PROBABILITY OF KILLING INFANTRY AND VEHICLES WITH FRAGMENTING AND DUAL PURPOSE MUNITIONS CARMONETTE V FORM 14 Vulnerability class Vehides Not responding to hostile fire State Net cover state Responding to hostile fire States 1, 2, or 3 12 11 1 1411 113 21 1 1 9 1 112 1 113 11 5

Fig. B8 - Form 14- Probability of Killing Infantry and Vehicles With Fragmenting and Dual Purpose Munitions

#### FORM 22 - SENSOR CLASS TABLES

Form 22 — Sensor Class Tables, has been revised to include the solid angle thresholds for both nonfiring and firing targets. The firing target information was formerly input on Form 30. Values for the maximum and minimum sensor ranges against nonfiring targets and for the maximum range against firing targets are entered on this form. The form has been expanded to provide for entries for six classes of sensors with a possible six types in each class. An example of the new Form 22 is shown in Fig. B9.

FORM 22 SENSOR CLASS TABLES

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Fig. B9 - Example of Form 22

# FORMS 23 - 29 - PROBABILITY OF CHANGES IN INTELLIGENCE

Forms 23 through 29 have been expanded to provide for entries for six sensor classes with a possible six types in each class. The order of entries in relation to the different states of target and observer activity and target solid angle class has been changed so that the order matches the computer program indexing order. Figures BlO through Bl6 show examples of the revised Forms 23 through 29.

FORM 23 PROBABILITY OF NOT DETECTING A TARGET

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Fig. BlO - Example of Form 23

FORM 24 PROBABILITY OF DETECTING BUT NOT PINPOINTING A TARGET

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Fig. Bll - Example of Form  $2^{l_t}$ 

FORM 25 PROBABILITY OF DETECTING AND PINPOINTING A TARFET

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Fig. Bl2 - Example of Form 25

FORM 26 ROBABILITY THAT A TARGET IS STILL PINPOINTED

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Fig. Bl3 - Example of Form 26

FORM 27 PROBABILITY THAT A TARGET WHICH HAS BEEN PINPOINTED IS LOST

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Fig. Bl4 - Example of Form 27

FORM 28
PROBABILITY THAT A DETECTED TARGET IS LOST

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Fig. B15 - Example of Form 28

FORM 29
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Fig. Bl6 - Example of Form 29

# FORMS 30 - 31 - INFORMATION PROBABILITIES ON FIRING TARGETS

Forms 30 and 31 have been reivsed to provide for only three solid angle classes. The order of the entries has been revised to conform to the order of the program indexing. The form has been expanded to provide for six sensor classes with up to six types in each class. Figures B17 and B18 show examples of Forms 30 and 31.

PROBABILITY OF ERRONEOUSLY PINPOINTING AN UNKNOWN TARGET THAT HAS FIRED

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		39 40 41 42 43 44 45 46 47 48 49 50 51 52 53 54 55 56 57 38 59 40 61 62 63 64 65 66 50 68 67 68 67 70 71 72	Target Solid Angle Class  1. A $<$ B, (from Form 22)  2. B $\downarrow \le$ A $<$ B, (from Form 22)  3. B $_2 \le$ A $<$ B, (from Form 22)  4. A $_2 \le$ B $_3 \le$ (from Form 22)
Observer Activity Neutralized Not Namedized	Target Solid An	5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 70 21 22 23 23 24 25 20 27 28 29 30 31 32 33 34 35 30 37 38 39 40 41	
		7.	2 2 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1

Fig. Bl7 - Example of Form 30

FORM 31 PROBABILITY OF PINPOINTING A TARGET THAT HAS FIRED FROM ERRONEOUS PINPOINT INFORMATION

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Fig. Bl8 - Example of Form 31

# FORM 36 - COMMAND AND CONTROL UNITS

Form 36-Command and Control Units (Blue and Red) is provided for the inputs of the required information concerning the CCS units.

A superior headquarters must be listed in columns 4 and 5 for each CCSU listed. For the superior headquarters being played in the game enter its own number.

In columns 6 through 21 a maximum of six CCS units that are subordinate to the CCS unit shown on that line can be entered. If the unit concerned does not have any subordinate units, i.e., forward observers or radar teams, no entry is required.

In columns 22 through 33 a maximum of eight subordinate weapons units can be listed. If the CCS unit concerned does not have any sub-ordinate weapon units of its own some other unit(s) should be listed to provide for continued life for the CCS unit if its original buddy unit should be killed.

In columns 34 and 35 a weapon unit is listed as the buddy unit for the CCS unit. The CCS unit will have the same initial position, follow the same orders, and move with the buddy unit listed. The buddy unit will normally be one of the subordinate weapon units of the CCS unit; however; if the CCS unit does not have any subordinate weapon units of its own, a weapon unit is selected to be its buddy unit. The same weapon unit can serve as the buddy unit for more than one CCS unit. These CCS units will then move together.

Columns 36 through 43 provide for the entry of sensor class, sensor type, and sensor height (in meters) for two different sensors.

Columns 44 to 46 are for the entry of the length of the communication cycle (in hundredths of a minute) for the CCS unit concerned. An X is entered in column 47 if the CCS unit is to have the capability of calling artillery fire.

Provision is made for an entry in column 48 to indicate authority to call helicopters to attack targets.

In columns 49 through 60 for artillery and columns 61 through 72 for helicopter, entries are made for the priority of targets against which these weapons will be called. The priorities for artillery and helicopters do not need to be the same.

Figure Bl9 shows an example of Form 36.

FORM 36 COMMAND AND CONTROL UNITS

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Fig. Bl9 - Form 36-Command and Control Units

## FORM 37 - IMAGE INTENSIFIER DATA

Forms 37A and 37B — Image Intensifier Data, are used to input the characteristics of the image intensifier class of the passive night vision devices used in the game. These data are critical to the probability of detection routine and calculations discussed in App A.

The entries in columns 18 through 50 of Form 37A are the values of the ordinate of the curve of the system modulation transfrer function at selected values of  $\gamma$  along the abscissa of the curve for the type device concerned. Figure A3 in App A shows the curves used in the night vision games. The values of  $\gamma_0$  to  $\gamma_{10}$  against which the ordinate values are determined must be eleven equally spaced values along the abscissa. In the current project values of 0 to 4 in steps of 0.4 are used.

The entries in columns 3 to 8, 15 to 17, and 51 to 62 do not at present enter into the calculation routine and are provided for possible future refinement of the routine.

The entries in columns 7 to 72 of Form 37B are the ordinate values of the curve of the photocathode tube sensitivity at selected points along the abscissa of the curve. Figure A4 in App A shows the curve used in the night vision games. The values of  $\lambda_0$  to  $\lambda_{10}$  must be eleven equally spaced values along the abscissa. The values used in the present project were 0.4 to 0.9 in steps of 0.05. These same values for  $\lambda_0$  to  $\lambda_{10}$  are used for determining the entries in Forms 38 and 39 for background and target reflectance.

Figures B20 and B21 show examples of Forms 37A and 37B.

FORM 37A IMAGE INTENSIFIER DATA

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Fig. B20 - Example of Form 37A

FORM 37B

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Fig. B21 - Example of Form 37B

FORMS 38 and 39 - BACKGROUND AND TARGET REFLECTANCE

Form 38 - Background, and Form 39 - Target, are used for the entries of the spectral reflectance of the types of background and of targets being played in the game. The values of  $\lambda_0$  to  $\lambda_{10}$  on each form at which the reflectance values are entered must be the same as the equivalent values used in preparing Form 37B. The data used in the present project are shown in Tables A2 and A3 in App A.

On Form 38 the background numbers in columns 1 and 2 are equated to the values of the concealment index for the grid square as established in the preparation of the terrain inputs for the game (see Step 5, App A, Vol II, RAC-R-28, CARMONETTE III Documentation). A determination must be made as to the type of background, i.e. sand, loam, grass, bushes, etc. to be related to the concealment indexes used.

On Form 39 the target types are identified in columns 1 and 2 and are the same as the target class numbers entered in columns 4 and 5 of Form 4.

FORM 38
BACKGROUND
CARMONETTE IV

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Values for  $\lambda_0$  to  $\lambda_{10}$  must be the same as the values of  $\lambda$  used as entry points on Form 37 for Photocathode Q( $\lambda$ )

Fig. B22 - Example of Form 38

FORM 39 TARGET

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Fig. B23 - Example of Form 39

## FORM 40 - ENVIRONMENTAL DATA

Form 40 is used for the entry of the scattering and absorption coefficients associated with the different light levels. The radar degradation factors are also entered on this form.

This form could be easily expanded to include other types of environmental conditions such as fog, dust, smoke, rain, and similar conditions. Such an expansion would require changes in the present programming.

## FORM 41 - RADAR CHARACTERISTICS

Form 41 is used for entry of the pertinent factors of radar performance that are used in the Radar Detection Routine.

FORM 40 ENVIRONMENTAL DATA

CARMONETTE IV

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Fig. B2 $^{\mu}$  - Example of Form  $^{\mu}$ O

FORM 41
RADAR CHARACTERISTICS

CARMONETTE IV.

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Fig. B25 - Example of Form 41

## Annex B2 EXAMPLE OF INPUTS

This annex is a listing of the computer inputs for one of the COBRA games, Treatment 4301. It is included to provide a potential user of the CARMONETTE simulation with examples of the kinds of numbers that are entered on the various input forms. To be understood it must be read in conjunction with the CARMONETTE input forms as described in the various volumes of documentation.

The form titles included here for information must not be included in a real game input deck.

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FORM 13 KILL PROBABILITIES AND FREFERED AMMUNITION

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FORM 14 FRAGMENTING AMMO KILL PROBABILITIES

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Form 32 continued

112NSTP RATE 6 SQRE 4735 113NCVE DOCT 1 RATE 6 115STAY INTL 2 FIRE 1 115STAY INTL 2 FIRE 1 115STAY INTL 27 118NCVE DOCT 1 RATE 6 119NCVE DOCT 1 RATE 7 120STAY IIME 5000 FIRE 5 121SKIP BACK 1 UNCO 1 124STAY IIME 5000 FIRE 1 125NSTP RATE 6 SQRE 4835 125NSTP RATE 6 SQRE 4835 125NSTP RATE 6 SQRE 4835 135NSTP RATE 6 SQRE 4835 135NSTP RATE 6 SQRE 4835 148NOVE DCCT 1 RATE 6 149DISM 100CT 1 RATE 6 149DISM 100CT 1 RATE 6 151SKIP BACK 1 UNTL 26 149DISM 100CT 1 RATE 6 151SKIP BACK 1 UNTL 26 153MOVE DCCT 1 RATE 6 154MOVE DCCT 1 RATE 6 155NSTP RATE 6 SQRE 4835 148NOVE DCCT 1 RATE 6 155NSTP RATE 6 SQRE 4835 155SKIP BACK 1 UNTL 27 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26 155SKIP BACK 1 UNTL 26	KIND SGRE 453 SGRE 313 SGRE 313 SGRE 414 KIND 414	T PRO TINO TO THE PROPERTY OF	4 6 FROR 6 PROR 7	t t t	HISN11113 HISN11113 HISN11114 HISN11117 HISN11119 HISN11124 HISN11124 HISN1124 HISN1125 HISN1126
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25NSTP RATE 6 SQRE 4537 26STAY TIME 5000 FIRE 1 27SKIP BACK 1 UNCD 24STAY INTL 20 25NSTP RATE 6 SQRE 4835 46STAY INTL 20 47NSTP RATE 6 SQRE 4835 49DISM 50STAY INTL 2 FIRE 1 51SKIP BACK 1 UNTL 26 52SKIF BACK 2 UNTL 26 53MOVE DCCT 1 RATE 6 54MCVE DCCT 1 RATE 6 55MOVE DCCT 1 RATE 7 55STAY TIME 5000 FIRE 7	77 7710	88 8			ISN112 ISN112 ISN112
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48MOVE DCCT 1 RATE 6 49DISM 50STAY INTL 2 FIRE 1 51SKIP BACK 1 UNTL 26 52SKIF BACK 2 UNTL 27 53MOVE DCCT 1 RATE 6 54MCVE DCCT 1 RATE 7 55STAY TIME 5000 FIRE 5	35 KIND		1		ISN114
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Form 32 continued

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EISTAY	EZSKIP	70KSTP	71STAY	72STAY	<b>73SKIP</b>	76NSTP	77 ST AY	78STAY	79SKIP	82STAY	E3ST AY	84SKIP	R7STAY	<b>PBSTAY</b>	89SKIP	SOSTAY	SISTAY	SSKIP	SSTAY	SESTAY	7 SKIP	8 STAY	9STAY	OSKIP	3STAY	4STAY	SSKIP	6STAY	7STAY	2C8SKIP	DISTP

Form 32 continued

ISN12	TON 101	15N121	121	<b>SN121</b>	ISN121	SN121	[SN121	SN122	[SN122	SN122	ISN122	ISN122	ISN128	ISN128	TSN122	TSN12	TSN12	TANA	ISN12	ISNIZ	ISN12	SN12	MISNIZ	[SN12	ISN12	ISN12	ISN12	ISN12	ISN12	ISN12	ISN12	ISN12	12	ISN12	
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Form 32 continued

SN126	ISN1ZE	ISN126	ISN127	ISN127	ISN127	ISN127	ISN127	ISN127	ISN127	Н	ISN127	ISN127	ISN128	ISN128	ISN129	ISN129	ISN129	ISN125	ISN129	ISN129	ISN129	<b>ISN129</b>	<b>ISN129</b>	ISN129	ISN130	ISN131	ISN131	ISN131	ISN131	ISN131	ISN131	ISN131	ISN131	ISN131	ISN135
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ETNST	EBNST	69STA	<b>70STA</b>	71SKI	<b>72SKI</b>	73SKI	74NST	75STA	<b>76SKI</b>	277SKIP	<b>785KI</b>	TSN61	<b>BDSTA</b>	81SKI	CO NST	91 NST	92STA	<b>53ST A</b>	<b>54SKI</b>	95 SKI	<b>56SKI</b>	SY NST	C8NST	<b>99STA</b>	DOSKI	10NST	11STA	12STA	13SKI	14SKI	15NST	<b>16NST</b>	17STA	18SKI	EDSTA

Form 32 continued

15 KIND	
KIND	SCRE 30
KIND         0 PROR         0 ALT         1         HISNI35           KIND         0 PROR         0 ALT         1         HISNI36           KIND         0 PROR         0 ALT         1         HISNI36           KIND         0 PROR         0 ALT         1         HISNI36           KIND         4 PROR         1         HISNI36         HISNI36           KIND         0 PROR         1         HISNI37         HISNI37           KIND         0 PROR         1         HISNI37         HISNI37           KIND         0 PROR         0 ALT         1         HISNI37           MISNI37         HISNI37	FIR
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KIND 4 PROR 1  KIND 0 PROR 1  KIND 0 PROR 0 ALT 1  MISNI36  MISNI37  KIND 0 PROR 0 ALT 1  MISNI37  KIND 0 PROR 0 ALT 1  MISNI37  KIND 0 PROR 0 ALT 1  MISNI37  MISNI37  MISNI37  MISNI37  MISNI37  MISNI37  MISNI37  MISNI37  MISNI37  MISNI37  MISNI38	<b>ORE 29</b>
KIND         4 PROR         1         MISNI36           KIND         0 PROR         0 ALT         1         MISNI36           KIND         0 PROR         1         MISNI37         MISNI37           KIND         0 PROR         0 ALT         1         MISNI37           MISNI37         MISNI37         MISNI37           MISNI38         MISNI38           MISNI38         MISNI38	9
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Form 32 continued

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FORM 33 FIRST ORDER AND STARTING LOCATION

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## Annex B3

### RUNNING GUIDE AND DATA STORAGE

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#### RUNNING GUIDE AND DATA STORAGE

#### INTRODUCTION

This annex is written specifically for guidance of the user of the CARMONETTE V computer simulation. It replaces Appendix E, CARMONETTE IV documentation.

No changes were made in the CARMONETTE IV processing of CCS Units, Surveillance, Target Selection, Position Disclosure, and Call Artillery Subroutines which were changed from CARMONETTE III.

Dismount and Remount Subroutines were added. This permits the dismounting or remounting of units on or off ground or air vehicles.

A skip order was added to skip if a given number of friendly units of a given vulnerability class became casualties.

Multiple warhead ammunition was added to artillery for use against vehicles.

The battle area was increased from 36 by 63 squares to 60 by 63 squares. The number of weapons units for each side was increased from 36 to 48 and the number of CCS units decreased from 27 to 15. The maximum number of subordinate units of a command unit was changed to six CCS units and eight weapons units.

The output (history) from the battle model for the postprocessor was changed from 5-word to 500-word blocks.

A helicopter submodel was added to provide attack helicopter, reconnaissance, and troop carrier capabilities. The following five subroutines enable CARMONETTE to be played with helicopter tactics:

- 1. LS2TG checks if LOS to the target(s) exists at maximum altitude.
  - 2. CHGVRT- computes time for ordered altitude change.
  - 3. MOVAIR- computes air movement time.
  - 4. ADJUST- modifies air movement time for a diagonal move.
- 5. CLHCPR- selects attack helicopter unit to provide fire support which has been called by a command unit.

The inputs, outputs, and tape file numbers for the programs are as follows:

#### First Preprocessor

Input cards. See data preparation guide.

- Tape 3. Output tape which is input to the second preprocessor. This tape will contain labeled commons CMAIN and INTER, whose lengths are stored in KONTRL (1) and (2), respectively, in BLOCK DATA STORE.
- Tape 2. The tape 3 (output) from a previous first preprocessor run. It is used as input if the previous input is to be updated. If updating is not required for the father or all of the sons the CHGE card should be followed immediately by the END card.

The END card will suppress the printing of the treatment data to be suppressed. To obtain the printout an ENDP card should be used.

#### Second Preprocessor

- Tape 3. The input tape. This is the output from the first preprocessor.
- Tape 2. The output tape. This is the input for the Battle Model. It contains the labeled common CMAIN, the length of which is stored in NWPERM in BLOCK DATA BATTLE in the Battle Model, and in NWPERM in BLOCK DATA DEFINE in the second preprocessor.

Card input is a single run option card. A zero (0) in column 2 will suppress the printing of the diagnostic treatment data. A one (1)

will permit printing. Columns 4-5 is the number of backgrounds between 1 and 16. In CARMONETTE V this was always zero. If the printing of only one or more than one treatment is desired, the treatment number is entered in Columns 7-10.

## The Battle Model

Tape 2. The input tape. This is the output from the second pre-

Tape 4. The output tape. This tape contains the history event processor. messages written during the running of the Battle Model,

Run Parameter Cards

The run parameters for each treatment are on separate cards. This card also controls the turning on of the debug feature. All numbers are decimal and right-adjusted in their fields. Col 1-3 maximum minutes of battle time per

replication.

Col 4-5 the number of replications to play.

Col 6-16 the seed for the first random number.

Col 17-20 treatment number to play.

Col 21-22 "X" coordinate on the battlefield.

Col 23-24 "Y" coordinate on the battlefield.

Col 25-28 a distance in meters.

Col 29 a side either 1-Blue or 2-Red.

Col 30 the number of units.

The last five fields above will cause the battle to terminate if more than the specified number of units of the given side reach the distance to the given square.

Col 31-34 the number of Red casualties to stop game.

Col 35-38 the number of Blue casualties to stop game.

Col 41-42 Indicator. In nonzero the debugging switch is turned on.

Col 44-47 beginning time for debugging printing.

Col 48-51 ending time for debugging printing.

In the last two fields above the numbers are scaled 26 and converted to decimal.

The last run parameter card must have the following:

Col 1-16 blank

Col 17-20 9999

Col 21-80 blank

#### The Postprocessor

Tape 4. The input tape. This is the history tape that was written during the battle simulation.

Input parameter cards. The first card contains a 1 in Col 1 if any history of any replication of any treatment is to be printed. A zero in Col 1 will print only a summary of all replications. Cols 2 to 5 contain the last treatment number to be processed. Cols 9 and 10 contain the replication number whose history is to be printed. A 99 entered in this field will cause the history of all replications to be printed. Columns 12 to 15 contain the treatment number whose replication(s) are to be printed. If this contains a zero (or blank) the history of the specified replication(s) of all treatments will be printed. If Cols 1 to 10 are nonzero, a second card with HISTRY in Cols 1 to 6 is required, otherwise the second card should be omitted.

## The Range Interval Postprocessor

This program lists the number of engagements (firings), number of rounds fired, troop and vehicle casualties for each weapon on both sides, for all target classes that were engaged, in range intervals of a specified number of meters. Total accumulated casualties are then listed by range interval from the longest to the nearest range. The averages for all replications of the treatment follow. The listing is for each replication of each treatment.

Tape 4. The input tape. The history tape from the Battle Model.

Input card lists the last treatment number to be processed in Cols 2 to 5, the range interval desired in Cols 7 to 10.

After all inputs for the CARMONETTE programs have been determined to be satisfactory, the Battle Model and the Postprocessor can be run as a job stream in a single run to decrease turnaround time. The maximum number of magnetic tape will be two on the job card. The Battle Model binary tape is copied onto a disc file, and then the binary tape unloaded. The requests for tapes 2 and 4 follow. At the end of the Battle Model run tape 2 is unloaded and tape 4 rewound. Loading and running of the postprocessor binary tape is then requested. The field length should be varied to be kept at the minimum required using RFL cards.

The line count should be indicated when the binary tape for either preprocessor or postprocessor is loaded; example, BIN (LC=XXXXXX), where X is an octal number. Normally 60,000 for each treatment listed for each preprocessor is sufficient. For the postprocessor 100,000 lines for a 50-minute battle for each treatment is sufficient.

#### SERVICE ROUTINES

#### Subroutine RWTAPE

RWTAPE is a FORTRAN subroutine to handle binary tapes. It provides read, write, backspace, skip, write file mark, and rewind facilities. Calls to RWTAPE for a particular file should not be mixed with FORTRAN  $I/\phi$  on the same file. RWTAPE has six entry points which are explained below.

Call RBT. To read binary a logical record of N central memory words, CALL RBT (fstloc, no. words, file no.)

where "fstloc" is the first location of a contiguous area that the data are to be read into, "no. words" is the number, N, of central memory words to be read, and "file no." is the number of one of the files that is defined on a REQUEST card and on the PROGRAM card. The file definitions

must be of the form TAPEx or TAPExx, where x is 1 to 9 and xx is 01 to 99. No other file definition will work. In all the calls, the number x or xx is substituted for the parameter "file no."

Call WBT. To write binary a logical record of N central memory words,

CALL WBT (fstloc, no. words, file no.)
where the parameters have a similar meaning to the above such that
"fstloc" is the first location from which "no. words" will be written
out onto "file no."

Call REPOS. To backspace the file N logical records, CALL REPOS (dummy, no. logical, file no.)

where "dummy" is an unused but required parameter, "no. logical" is the number of logical records to be backspaced and "file no." is as before.

Call WFMK. To write a file mark:

CALL WFMK (dummy, dummy, file no.)

CALL EMINDE (dummer dummer file

CALL RWNDT (dummy, dummy, file no.)

Call RBT. To skip one logical record:

CALL RBT (dummy, O, file no.)

#### UTILITY ROUTINES

The following seven routines are coded in the CDC 6000 series machine language COMPASS and perform packing, bit setting, and bit testing operations.

All seven functions employ the same bit numbering convention. Bits are numbered from 1 to 60, counting the bits from right to left, as shown below.

60, 59, 58 ... 3, 2, 1

In all function calls, variable names have the following meanings:

Name	Description		
IDATA	Location containing data to be mod-		
	ified, tested, etc.		
NUM	A number specifying a contiguous		
	number of bits (not to exceed 60)		
NB	A bit number (1 to 60)		
INSRT	Word containing a bit string to be		
	inserted into another word.		

### IØNBIT

IØNBIT will set to one bit number NB of IDATA. A copy of the modified IDATA is returned to I.

I = IØNBIT (IDATA, NB)

### **IØFFBT**

IMFFBT will set to zero bit number NB of IDATA. A copy of the modified IDATA is returned to I.

I = IØFFBT (IDATA, NB)

#### KBIT

KBIT will return the value true (a non-"plus zero" value) if bit number NB of IDATA is a one, and will return the value false (plus zero) otherwise. KBIT must be declared logical.

IF (KBIT (IDATA, NB))...statement....

IF (.NOT.KEIT (IDATA, NB)) will work only if the program was compiled by FORTRAN Extended.

#### NBITS

NBITS will return a count of the number of one bits in IDATA.

I = NBITS (IDATA)

#### KGET

KGET copies NUM bits of data starting at the NB<sup>th</sup> bit position of IDATA and returns the copied bits right justified to I. IDATA is not modified.

109 .

I = KGET (IDATA, NUM, NB)

#### KPUT

KPUT inserts the rightmost NUM bits of INSRT into a copy of IDATA beginning with bit number NB. IDATA is not modified.

I = KPUT (IDATA, NUM, NB, INSRT)

#### IDATA

To modify IDATA, code as:

IDATA = KPUT (IDATA, NUM, NB, INSRT)

No error checking is performed by any of the functions, hence the user is responsible for proper use. Results will be unpredictable if either NUM or NB contains a parameter that exceeds 60. Further, unless the user specifically desires wrap-around from the high to low order part of the word, NUM should not exceed 61-NB.

## DATA STORAGE ALLOCATION

## Variable Words

Contents	Variable	Words
Game Control Data	JGAME	24
Terrain Characteristics	JIAND	2112
Mission Orders	JMISNS	999
Miscellaneous Data	JMISC	31
Line of Sight Info	jløs ·	48
Side Parameters	JSIDEP	78,2
Unit Control Data	JCNTRL	11,48,2
Unit Attributes	JATRIB	48,2
Unit Characteristics	JUCHAR	10,48,2
Unit Intelligence	JINTEL	8,48,2
Command Control and Surveillance Unit Data	JCCS	6,15,2
Command Control and Surveillance Unit Characteristics	JCMD	7,15,2
Weapons Basic Data	JWEAP	3,36
Tactical Standard Deviations	JTACSD	12,28
Probabilities of Kill, Non-Frag Ammo	JPKILL	2,2,28
Probabilities of Kill, Frag Ammo	JFRAG	2,18
Target Detection Data	JDTECT	31,6,6
Cover and Concealment Conversion Data	JCNVRT	6,6
Ground Mobility Data	JGMØB	11,5
Air Mobility Data	JAMØB ,	5,3
Visual Devices, Detection Data	JVISA	6,2
Minimum Target Dimension	JDIM	3
I. I. Devices Magnification	JDMAG	1
Image Intensifier, Constant Kl	CKL	6
Image Intensifier, Constant K2	CK2	6

Contents	Variable	Words	
Image Intensifier Devices, Modulation Transfer Function	EDMIF	. 6	
Image Intensifier Devices, Computed Integral Approximation	P2	6	
Image Intensifier Devices, Background Reflectance	BREFM1.	6,16	
Image Intensifier Devices, Target Reflectance	TREFM2	6,16	
Integral of Relative Luminosity, Night Sky Brightness	, Pl	3	
Visual Devices, Background Reflectance	BREFM3	16	
Visual Devices, Target Reflectance	$\mathtt{TREFM}^{\!L}$	16	
Night Sky Brightness, Wavelengths .4 to .9	SBK	11	
Radar Characteristics	JRADAR	6	
Run Control Data	JRUN	14	
Arty Target Priority	IARTY	6,15,2	
Helo Target Priority	$\mathtt{IHEL} \phi$	6,15,2	
Special Data	JDATA	17	
Visibility Condition Data	JDMAG	1	

## Game Control Data JGAME (24)

Twenty four words are used to control the game. Each is stored in a unique word for ease of control.

Description	6400 Local	6400
Current Treatment No.	variable	Word no.
Current Event Command Unit	NTR	1
	IFHQ	2
Current Time XXX,XXXX	KTIME ,	3
Current Event Side	MS IDE	4
Current Event Unit	MUNIT	5
Current Event Unit X coordinate	IXS	6
Current Event Unit Y coordinate	IYS	7
Current Event Unit Altitude	IZS	8
Current Event Code	KC <b>Ø</b> DE	9
Current Event Message Code	L <b>ø</b> B	10
Current Weapon (Main, B, C, D)	MWB	11
Opposite Side (3-MSIDE)	IØPP	12
Current Random Number	NUMR	13
Meters per grid	MGRID	14
Number of Blue Weapon Units	JBLUE	15
Number of Red Weapon Units	JRED	16
Total Number of Enemy Weapon Units	ITNBR	17
Total Number of Blue Command Units	JCBLUE	18
Total Number of Red Command Units	JCRED	19
Total Number of Command Units	ICNBR	20
Current Number of Blue Casualties (men)	KASBLU	21
Current Number of Red Casualties (men)	KASRED	22
Current Event Sensor (A or B)	MSENS	23
Not used		24

## Terrain Characteristics JLAND (2112)

A 60 by 63 terrain grid is represented with two grids per 6400 word in 2112 words.

	6400 Local	6400
Description	variable	Bit no.
Word 1 Grid X1, Y1 and X2, Y1		
Grid X1, Y1		
Elevation (0-4095 ft)	LELEV	60-49
Vegetation (0-63 ft)	LVEG	48-43
Road trafficability (0, 1, 2, 3)	LRØAD	42-41
Cross country trafficability (1, 2, 3)	LTRAF	40-39
Cover Index (0-15)	lcøv .	38-35
Concealment index (0-15)	LCØN	34-31
Grid X2, Yl		
Elevation (0-4095 ft)	LELEV	30-19
Wegetation (0-63 ft)	LVEG	18-13
Road trafficability (0, 1, 2, 3)	LRØAD	12-11
Cross country trafficability (1, 2, 3)	LTRAF	10- 9
Cover index (0-15)	·Lcøv	8 <b>-</b> 5
Concealment index (0-15)	lcøn	4- 1

## Word 30 Grid X59, Yl and X60, Yl

See Word 1 for format

### Scenarios JMISNS (999)

A series of orders for each unit simulated is defined as the game scenario. Each unit has its next sequential order number stored in Word 10 of unit control data (JCNTRL). Each order defines its subsequent order either explicitly or conditionally. Any combination of units on either side may utilize the same sequence of orders. No provision exists for permitting a unit to follow a sequence and then diverge to follow a different sequence. (All units given the same initial order number must follow that same sequence.) (Input format limits the total number of orders to 999.)

Description	6400 Local variable	6400 Bit no.
Moving order mode	MWG	36-34
Moving order altitude	MWI	33-31
Moving order doctrine	MWJ	30-28
Moving order speed	<b>M</b> W K	27-25
Stay protect interval	MWSPI	33-25
Conditional order	MWR	24-22
Conditional order	<b>M</b> WB	21-19
X Coordinate	MWX	18-13
Y Coordinate	MWY	12- 7
Until battle time	MWTIME	18- 7
For battle interval	MNTIME	18- 7
Kind of fire	MWF).	6- 4
Priority of fire	MWF2	3 <b>-</b> 1

### Miscellaneous Data JMISC (31)

The following miscellaneous data are stored as follows:

Desc	cript:	ion		6400 Local variable	6400 Bit no.
	Word	l Ordere	d Moving Time	Ground	
Ordered moving	time,	Rate O	3XX <sup>V</sup> XXXX	LØMTG(1)	60-41
Ordered moving	time,	Rate 1	3xx <sup>V</sup> xxxx	LØMTG(2)	40-21
Ordered moving	time,	Rate 2	3XX <sup>V</sup> XXXX	LØMTG(3)	20- 1
	Word	2 Ordered	d Moving Time	Contd	
Ordered moving	time,	Rate 3	3XX <sup>V</sup> XXXX	LØMTG(4)	60-41
Ordered moving	time,	Rate 4	3XX <sup>V</sup> XXXX	LØMTG(5)	40-21
Ordered moving	time,	Rate 5	3xx <sup>V</sup> xxxx	LØMTG(6)	20- 1
	Word	3 Ordered	d Moving Time	Contd	
Ordered moving	time,	Rate 6	3XX <sup>x</sup> XXXX	LØMTG(7)	60-41
Not used			, ,	····	40- 1

	6400 local	6400
Description		bit no.
Word 4 Ordered Movin	g Time Air	
Ordered Moving Time, RATE O	LØMTA(1)	60-41
Ordered Moving Time, RATE 1	LØMIA(2)	40 <b>-</b> 21
Ordered Moving Time, RATE 2	LØMTA(3)	20- 1
Word 5 Ordered Movin	g Time Air Contd	
Ordered Moving Time, RATE 3	LØMTA(4)	50-41
Ordered Moving Time, RATE 4	LØMIA(5)	40 <b>-</b> 21
Ordered Moving Time, RATE 5	LØMTA(6)	20- 1
Word 6 Ordered Movin	g Time Air Contd	
Ordered Moving Time, RATE 6	LØMTA(7)	60-41
Not used	LØMTA	40- 1
Word 7 Vulnerability	Range Thresholds	
Near range threshold	KSVRN	60-49
Far range threshold	KSVRF	48-31
Not used		30- 1
Word 8 Vulnerabilit	y Class l, Seriously V	<u>/ulnerable</u>
Target Class 1, d ≤ R1	MCVTS(1,1)	1
Target Class 2, d ≤ Rl	MCVTS(2,1)	2
Target Class 3, d ≤ Rl	MCVTS(3,1)	3
Target Class 4, d ≤ Rl	MCVTS(4,1)	4
Target Class 5, d ≤ Rl	MCVTS(5,1)	5
Target Class 6, d ≤ Rl	MCVTS(6,1)	6
Target Class 7, d ≤ R1	MCVTS(7,1)	7
Target Class 8, d ≤ Rl	MCVTS(8,1)	8
Target Class 9, d ≤ Rl	MCVTS(9,1)	9
Target Class 10,d ≤ R1	MCVTS(10,1)	10
Target Class ll,d ≤ Rl	MCVTS(11,1)	11
Target Class 12,d ≤ R1	MCVTS(12,1)	12
Target Class 13,d ≤ Rl	MCVTS(13,1)	13

JMISC continued	6400 local	6400
Description	variable	bit no.
Word 8 continued	d	
Target Class 14, d ≤ R1	MCVTS(14,1)	14
Target Class 15, d ≤ Rl	MCVTS(15,1)	15
Target Class 16, d ≤ R1	MCVTS(16,1)	16
Target Class 1, R1 < d ≤ R2	MCVTS(1,2)	17
Target Class 2, $R1 < d \le R2$	MCVTS(2,2)	18
Target Class 3, Rl < d ≤ R2	MCVTS(3,2)	19
Target Class 4, Rl < d ≤ R2	MCVTS(4,2)	20
Target Class 5, $R1 < d \le R2$	MCVTS(5,2)	21
Target Class 6, R1 < d ≤ R2	MCVTS(6,2)	22
Target Class 7, R1 < d ≤ R2	MCVTS(7,2)	23
Target Class 8, Rl < d ≤ R2	MCVTS(8,2)	24
Target Class 9, Rl < d ≤ R2	MCVTS(9,2)	25
Target Class 10, R1 < d ≤ R2	MCVTS(10,2)	26
Target Class 11, R1 < d ≤ R2	MCVTS(11,2)	27
Target Class 12, R1 < d ≤ R2	MCVTS(12,2)	28
Target Class 13, R1 < d ≤ R2	MCVTS(13,2)	29
Target Class 14, R1 < d ≤ R2	MCVIS(14,2)	30
Target Class 15, Rl < d ≤ R2	MCVTS(15,2)	31
Target Class 16, R1 < d ≤ R2	MCVTS(16,2)	32
Target Class 1, d > R2	MCVTS(1,3)	33
Target Class 2, d > R2	MCVTS(2,3)	34
Target Class 3, d > R2	MCVTS(3,3)	35
Target Class 4, d > R2	MCVTS(1,3)	36
Target Class 5, d > R2	MCVTS(5,3)	37
Target Class 6, d > R2	MCVTS(6,3)	38
Target Class 7, d > R2	MCVTS(7,3)	
Target Class 8, d > R2	MCVTS(8,3)	
Target Class 9, d > R2	MCVTS(9,3)	41
Target Class 10, d > R2	MCVTS(10,3)	42

JMISC continued

Description	6400 local variable	6400 bit no.
Word 8 continued		
Target Class 11, d > R2	MCVTS(11,3)	43
Target Class 12, d > R2	MCVTS(12,3)	44
Target Class 13, d > R2	MCVTS(13,3)	45
Target Class 14, d > R2	MCVTS(14,3)	46
Target Class 15, d > R2	MCVTS(15,3)	47
Target Class 16, d > R2	MCVTS(16,3)	48
Probability of Indicating Death when Killed	KBURN	60-55

#### Word 9 Vulnerability Class 2, Seriously Vulnerable

See Word 8 for format

. .

Word 19 Vulnerability Class 12, Seriously Vulnerable

See Word 8 for format

#### Word 20 Vulnerability Class 1, Moderately Vulnerable

See Word 8 for format (does not include KBURN)

MCTM(1,1)

• • • •

#### Word 31 Vulnerability Class 12, Moderately Vulnerable

See Word 8 for format (does not include KBURN)

MCVTM(16,3)

### Line of Sight Information JLØS (48)

The line of sight information is contained in 48 words. The word number in the array corresponds to the Blue unit number. The bit number in each word corresponds to the Red unit number. A bit is on if the pair is intervisible. Bits 49-60 in each word are not used.

### Side Parameters JSIDEP (78,2)

The side parameters consist of 78 words. The first four words contain the side's thresholds for response to enemy fire. The next word contains the "white eye" range and suppressive fire area for the side. The next word contains the exit points. The next 16 words contain the moving probabilities for each mobility class and movement doctrine. Fifty-six words describe the priority of targets for weapons assigned to the side.

Description	6400 local variable	6400 bit no.
Word 1 Infantry Thresholds		
Infantry pinned down, D.F. + Ind Fire	LLTF1	60-48
Infantry partially neut., D. Fire	LLTF2	47-36
Infantry partially neut., Ind Fire	LLTF3	35 <b>-</b> 24
Not used		23- 1
Word 2 Aircraft Thresholds		
Aircraft abort firing run	LLTHF	60-49
Aircraft drop to tree-top altitude	LLTHN	48-37
Not used		36 <b>-</b> 1
Word 3 Armored Thresholds		
Light armored vehicles D. Fire	LLTM2	60-49
Light armored vehicles Ind Fire	LLTM2	48-37
Heavy armored vehicles D.Fire	LLTM3	36 <b>-</b> 25
Heavy armored vehicles Ind Fire	LLTM3	24-13
Not used		12- 1

JSIDEP continued		
Description	6400 local variable	6400 bit no.
Word 4 Open Vehicles Thresho	olds	
Open vehicle pinned down	LLTZ1	60-48
Open vehicle partially neut., D. fire	LLTZ2	47-36
Open vehicle partially neut., Ind fire	LLTZ3	35-24
Not used		23 <b>-</b> 1
Word 5 White Eye Range & Sur	pression Area	
White eye range	KWER	60-47
Suppressive fire search radius	LASQ	46 <b>-</b> 35
Not used		34- 1
Word 6 Escape Points		
X Coord of 1st Escape Point	LEXITX(1)	60-55
Y Coord of 1st Escape Point	LEXITY(1)	54 <b>-</b> 49
X Coord of 2nd Escape Point	LEXITX(2)	48-43
Y Coord of 2nd Escape Point	<pre>LEXITY(2)</pre>	42-37
X Coord of 3rd Escape Point	LEXITX(3)	36 <b>-</b> 31
Y Coord of 3rd Escape Point	LEXITY(3)	30 <b>-</b> 25
Not used		24- 1
Word 7 Moving Probabilities		
Mobility Class O, Moving Doctrine 1		
No tgt No cover	LMVPRB(1)	60 <b>-</b> 55
Yes tgt No cover	LMVPRB(2)	54 <b>-</b> 49
No tgt Yes cover	LMVPRB(3)	48-43
Yes tgt Yes cover	LMVPRB(4)	42 <b>-</b> 37
Mobility Class 1, Moving Doctrine 2 No tgt No cover	LMVPRB(1)	36 <b>-</b> 31
Yes tgt No cover	LMVPRB(2)	30 <b>-</b> 25
. No tgt Yes cover	LMVPRB(3)	24-19
Yes tgt Yes cover	LMVPRB(4)	18-13
Not used		12- 1

6400 loc	cal 6	5400
variabl	Le 1	bit no.

Description

### Word 8 Moving Probabilities continued

Mobility Class O, Moving Doctrines 3 and 4

See Word 7 for format

Word 22 Moving Probabilities continued

Mobility Class 7, Moving Doctrines 3 and 4
See Word 7 for format

### Words 23 and 24 Weapon #9 Priority Lists

Targe	t Class	lst	priority,	lst	sought	NCT(1)	60-56
Targe	t Class	lst	priority,	2nd	sought	NCT(2)	55 <b>-</b> 51
Targe	t Class	lst	priority,	3rd	sought	NCT(3)	50-46
Targe	t Class	lst	priority,	4th	sought	NCT(4)	45-41
Targe	t Class	lst	priority,	5th	sought	NCT(5)	40-36
Targe	t Class	lst	priority,	6th	sought	NCT(6)	35-31
Targe	t Class	2nd	priority,	lst	sought	NCT(1)	30 <b>-</b> 26
Targe	t Class	2nd	priority,	2nd	sought	NCT(2)	25-21
Targe	t Class	2nd	priority,	3 <b>r</b> d	sought	NCT(3)	20-16
Targe	t Class	2nd	priority,	4th	sought.	NCT(4)	15-11
Targe	t Class	2nd	priority,	5th	sought	NCT(5)	10- 6
Targe	t Class	2nd	priority,	6th	sought	NCT(6)	5 <b>-</b> 1
Targe	t Class	3rd	priority,	lst	sought	NCT(1)	60-56
Targe	t Class	3rd	priority,	2nd	sought	NCT(2)	55 <del>-</del> 51
Targe	t Class	3rd	priority,	3rd	sought	NCT(3)	50-46
Targe	t Class	3rd	priority,	4th	sought	NCT(4)	45-41
Targe	t Class	3rd	priority,	5th	sought	NCT(5)	40-36
Targe	t Class	3rd	priority,	6th	sought	NCT(6)	35-31
Not u	sed						30- 1

### Words 25 and 26 Weapon #10 Priority Lists

See Words 23 and 24 for format

	6400 local	6400
Description	variable	bit no.

### Words 77 and 78 Weapon #36 Priority Lists

See Words 23 and 24 for format

## Unit Control Data JCNTRL (11, 48, 2)

Unit control information is stored in 11 words. One word contains the time and event that will occur next for this unit. (If the next event is boundary crossing, the rest of the word contains the altitude increment and movement time from the boundary to the center of the next square.) Six words contain the unit's clocks; one word contains the number of rounds received; one word contains the current order; and one word contains the unit's location and a pointer to the next order. The last word contains the number of firings of the main weapon until the next order change and line of sight to enemy weapon units.

Degeninties		6400 local	6400
Description		variable	bit no.
Word 1 Next Event			
Not used			60-31
Time-boundary to center of square	XXXXXXX	ITBC	30-10
Altitude change		na	9 <b>-</b> 1
Word 2 Activities			
Control time	XXXXXXX	LCCLK	60-40
Control code	,,	LCCDE	39 <b>-</b> 31
Tactic time	XXXXXXX	LTCLK	30-10
Tactic code	,,	LTCDE	9 <b>-</b> 1
Word 3 Surveillance	Devices		
Surveillance #1 time	XXX XXXX	LSCLK(1)	60-40
Surveillance #1 code	· X	LSCDE(1)	39 <b>-</b> 31
Surveillance #2 time	xxxxxx	LSCLK(2)	30-10
Surveillance #2 code		LSCDE(2)	9 <b>-</b> 1

Description		6400 local variable	6400 bit no
Word 4 Main	Weapon		
Event time	XXX <sub>x</sub> XXXX	IWCLK(1)	60 10
Event code	X	LWCDE(1)	60-40
Loading time	xxx <sup>v</sup> xxxx .	LLCLK(1)	39-31
Loading code	Λ	LLCDE(1)	30 <b>-</b> 10 9 <b>-</b> 1
Word 5 Weapo	n B	,	<i>)</i>
See Word 4 for format		IWCLK(2)	
Word 6 Weapon	n C	(2)	
See Word 4 for format		IWCLK(3)	
Word 7 Weapor	<u>1 D</u>		
See Word 4 for format		IWCLK(4)	
Word 8 Fire R	Received		
Direct fire received interval		LLRD3	60-51
Direct fire received interval		LLRD2	50-41
Direct fire received interval	D	LLRD1	40-31
Indirect fire received interv		LLRA3	30-21
Indirect fire received interva		I LRA2	20-11
Indirect fire received interva	al D	LLRA1	10- 1
Word 9 Current	t Order		
Skip order time		LPCT	60-49
Current order number		LTAG	48 <b>-</b> 37
Moving order mode		MWG	36 <b>-</b> 34
Moving order altitude		MWI	33-31
Moving order doctrine		MWJ	30 <b>-</b> 28
Moving order speed		MWK	27 <b>-</b> 25
Stay protect interval		MWSPI	33 <b>-</b> 25
Conditional order		MWR	24 <b>-</b> 22
Coordinate		MWX	18-13
Coordinate		MWY	12- 7

JCNTRL continued		
Description	6400 local variable	6400 bit no.
Word 9 continued	var rabite	DIC NO.
Until battle time	MUTIME	18- 7
For battle interval	MNTIME	18- 7
Kind of fire	MWFI	6- 4
Priority of fire	MWF2	3 <b>-</b> 1
Word 10 Location and Next Ord	ler ,	
Current X coordinate	IXS	60-55
Original X coordinate	na	54 <b>-</b> 49
Current Y coordinate	IYS	48-43
Original Y coordinate	na.	42-37
Current altitude	I7S	36 <b>-</b> 25
Next (or last) X coordinate	IXNEW	24 <b>-</b> 19
Next (or last) Y coordinate	IYNEW	18-13
Next order number	LTAGK	12- 1
Word 11 Activities Record		
Remaining firings until order change	LSMCHK	60-49
Line of sight to enemy weapon units		48- 1

The following event codes are used in the control words:

Event	Decimal	Octal (9 bits)
Decision	0	000
Boundary crossing	8	010
End dismount	16	020
Surveillance	24 + MSENS#	O3j (j=MSENS)
Change altitude	32	040
Communication	40	050
Target Selection	64 + MWP*	lOi (i=MWP)
End aiming	72 + MWP	lli (i=MWP)
Impact	96 + MWP	14i (i=MWP)
Assessment	112 + MWP	16i (i=MWP)
End loading	192 + MVP	30i (i=MMP)

## (Event codes continued)

Event	Decimal	Octal (9 bits)		
Tactics Out of ammo	320	500		
out of ammo	328	510		

#MSENS is assigned sensor group: Sensor A=1, Sensor B=2. \*MWP is assigned weapon group: Main = 1; B= 2; C=3; D=4.

## Unit Attributes JATRIB (48, 2)

Unit attributes are stored in one word per unit. A bit is on if the unit has the attribute described.

Attribute	6400 local variable	6400
Ammunition contingency orders		bit no.
Escape orders	IACL	1
Call artillery	LBUG	2
Infantry	LKHQ	3
Troop carrier	INF	4
Dismount troops when hit	NOT. NTCU	5
Aircraft	LTØFF	6
Unable to fire	LLAC	7
Unable to move	LFIRE	8
Unit can provide air support	I™ØB	9
Unit is dead	IASPT	10
Unit is dismounting	LSDEAD	11
Unit is moving	LFDISM	12
Unit can provide artillery support	LFMOVE	13
Unit is busy (responding to fire)	LSPT	14
Not used	LFR	15
Unit may not fire until "white eye range"		16
Unit is pinned down	LEYE	17
Unit is partially neutralized DF	LFR1	18
Unit is partially neutralized indirect fire	LFR2	19
Unit is burning	LFR3	20
Unit has burned	LBURN	21
	LHBURN	22

## JATRIB continued

Attribute	6400 loca variable	
Main weapon is aimed	770 734	
Main weapon has suppressive fire target	KA IM	23
Main weapon is direct fire	LTAREA	24
Main weapon requires guidance	KDF	25
Weapon B is aimed	LGM	26
Weapon B has suppressive fire target	KAIM(2)	· 27
Weapor B is direct fire	LTAREA(2)	28
Weapon B requires guidance	KDF(2)	29
Weapon C is aimed	LGM(2)	30
	KAIM(3)	31
Weapon C has suppressive fire target	LTAREA(3)	32
Weapon C is direct fire	KDF(3)	33
Weapon C requires guidance	IGM(3)	34
Weapon D is aimed	KAIM(4)	35
Weapon D has suppressive fire target	LTAREA(4)	36
Weapon D is direct fire	KDF(4)	-
Weapon D required guidance	LGM(4)	37
Unit is mounted	LIMBØ	38
Unit is an artillery support unit (i.e., does not exist as a separate entity	LART	39 40
Potential carrier	T Tomas	
Unit is on diagonal move	LPTC	41
Present moving rate (m/sec) X_XXX	LDIAG	42
	MVEL	60-43

# Unit Characteristics JUCHAR (10, 48, 2)

Ten words are used to describe the unit characteristics. Two words contain unit classification data and eight words contain weapons data.

JUCHAR cont	C	ln	u	ed
-------------	---	----	---	----

Description	6400 local	6400
	variable	bit no
Word 1 Unit descriptors		
Original number of men	LMAN	60-55
Current number of men	KMAN	54 <b>-</b> 49
Original number of vehicles	LVEH	48-43
Current number of vehicles	KVEH	42 <b>-</b> 37
Number of drivers	KMI	36 <b>-</b> 31
Max number of men/vehicle	MMPV	
Unit sensor height	LTALL	30 <b>-</b> 25 .
Unit deployment radius	IRADU	24~19
Apparent radius for detection	lcøn1	18-13
Apparent radius for hit	LCØVI	12 <b>-</b> 7 6 <b>-</b> 1
Word 2 Unit descriptors con	•	
Target class	· · · · · · · · · · · · · · · · · · ·	
Vulnerability class	LCT	60-55
Element size class	LCV	54-49
Mobility class	IRAD	48 <b>-</b> 43
Fire response class	LCM	42 <b>-</b> 37
Sensor #1 class	IFRT	36 <b>-</b> 31
Sensor #1 type	LSC	<b>30-</b> 28
Net cover index	LST	<b>27-</b> 25
Number of assigned weapon types	rc\delta s	24-19
Superior unit number	na /	18-13
Fraction of time unavailable to provide	MBØSS	12- 7
support fire		
Word 3 Main Hooney D	LFTU	6- 1
Word 3 Main Weapon Description	<u>on</u>	
Weapon type	MWPT	60 <b>-</b> 55
Number of weapons	KTUBE	54-49
Target number	itnø	48-43
Target X coordinate	IXT	42-37
Target Y coordinate	IYT	36-31
Trigger pull pinpoint status (not used)	ITP	30-25

JUCHAR continued		
Description	6400 local variable	6400 bit no.
Word 3 continued		
Ammo type	IA ·	24-19
Hit signal	JHIT	18-13
Number of men firing	NMF	12- 7
Number of consecutive shots	NCS	6- 1
Word 4 Main Weapon Description	continued	
Ammunition type 1 remaining	LAMW1	60-49
Ammunition type 1 originally	na	48-37
Ammunition type 2 remaining	IAMM2	36 <b>-</b> 25
Ammunition type 2 originally	na	24-13
Number of rounds fired at last target	LRNDS	12- 1
Word 5 Weapon B Description		
See Words 3 and 4 for format		
Word 6 Weapon B Description con-	tinued	
See Words 3 and 4 for format		
Word 7 Weapon C Description		
See Words 3 and 4 for format		
Word 8 Weapon C Description conf	inued	
See Words 3 and 1; for format		
Word 9 Weapon D Description		-
See Words 3 and 4 for format		
Word 10 Weapon D Description cont	inued	
See Words 3 and 4 for format		

### Unit Information JINTEL (8, 48, 2)

Unit information concerning all enemy units is stored in eight words. Within each word, six enemy units are represented with ten items of information represented by the bits. A bit is on if the unit has the item of information concerning the enemy unit.

Information	6400 local variable	6400 bit no.
Enemy unit known dead	LDEAD	1
Enemy unit detected (nearest square)	MI2	2
Enemy unit identified (erroneous pinpoint)	MI3	3
Enemy unit recognized (accurately pinpointed)	MI4	14
Enemy unit firing at other units interval D	LKEEl	5
Enemy unit firing at other units interval D-1	LKEE2	6
Enemy unit firing at other units interval D-2	LKEE3	7
Enemy unit firing at this unit interval D	LLEE1	8
Enemy unit firing at this unit interval D-1	LLEE2	9 ·
Enemy unit firing at this unit interval D-2	LLEE3	10

		Ene	my unit n	numbers		
Unit No. 1	60 - 51	50 - 41	40 - 31	30 <b>-</b> 21	20 - 11	10 - 1
Word 1	6	5	14	3	2	1
Word 2	12	11	10	9	8	7
Word 3	18	17	16	15	14	13
Word 4	24	23	22	21	20	19
Word 5	30	29	28	27	26	25
Word 6	36	35	34	33	32	31
Word 7	42	41	40	39	38	37
Word 8	48	47	46	45	44	43

## Command, Control, and Surveillance Unit Data JCCS (6, 15, 2)

Six words are used to store the information for the command units. If the event is boundary crossing the rest of the word contains the time from boundary to center and the altitude increment. The next word contains the unit control clock and the tactics clock. The third word

### JCCS continued

contains the surveillance clocks for the two surveillance devices permitted each CCS unit. The fourth word contains the communications clock. The last two words contain the current order and the location for the unit.

Description		6400 local variable	6400 bit no.
Word 1	Next event		020 110
Master clock	XXXXXX	LMCLK	60-40
Master code	7	, na	39-31
Time from boundary to center	XXX <sup>x</sup> XXXX	ITBC	30-10
Altitude increment	~	na	9 <b>-</b> 1
Word 2	Activities		
Control time	XXX <sup>V</sup> XXXX	LCCLK	60-40
Control code	,	LCCDE	39 <b>-</b> 31
Tactic time	$xxx^{\vee}xxxx$	LTCLK	30-10
Tactic code		LTCDE	9 <b>-</b> 1
Word 3	Surveillance		
Surveillance device #1 time	XXX <sup>X</sup> XXXX	LSCLK	60-40
Surveillance code	Λ	LSCDE	39-31
Surveillance device #2 time	XXX <sup>V</sup> XXXX	LSCLK	30-10
Surveillance code	7	LSCDE	9- 1
Word 4	Communications		
Communications time		LØCLK	60-40
Communications code		L <b>¢</b> CDE	39-31
Communications interval		INTC	30-10
Not used			9 <b>-</b> 1
Word 5	Current crder		
Skip order time		LPCT	60-49
Current order number		LTAG	48-37
Moving order mode		MvG	36-34
Moving order altitude		MWI	33-31
Moving order doctrine	1	MWJ	30-28

Description		6400 loca variable	
Word 5	Current order contin	nued	
Moving order speed		MWK	27-25
Conditional order		MWR	24-22
Conditional order		MWB	21-19
X coordinate		MWX	18-13
Y coordinate	. ,	MWY	12- 7
Kind of fire		MWFl	6- 4
Priority of fire		MWF2	3 <b>-</b> 1
Word 6	Location and Next Or	rder	
Current X coordinate		IXS	60-55
Original X coordinate	- 1 - 1	na	54-49
Current Y coordinate		IYS	48-43
Original Y coordinate		na	42-37
Current altitude		IZS	36 <b>-</b> 25
Next (or last) X coordinate		IXNEW	24-19
Next (or last) Y coordinate		IYNEW	18-13
Next order number		LTAGK	12- 1

## Command Unit Characteristics JCMD (7, 15, 2)

Each command unit is described in seven words, as described below.

Description		6400 local variable	6400 bit no.
Word 1	Characteristics	tinds till. A 1 Million man	
Superior HQ number		MBØSS	60 <b>-</b> 55
Number of subordinate HQ (1-8)		NSUB	5 <b>4-</b> 49
Subordinate HQ #1		MYLT(1)	48-43
Subordinate HQ #2		MYLT(2)	42-37
Subordinate HQ #3		MYLT(3)	36-31
Subordinate HQ #4		MYLT(4)	30-25
Subordinate HQ #5	•	MYLT(5)	24-19

JCMD continued		
Description	6400 local variable	6400 bit no.
	teristics continued	DIC NO.
Subordinate HQ #6	MYLT(6)	18-13
Subordinate unit #1	MYMEN(1)	12 <b>-</b> 7
Subordinate unit #2	MYMEN(2)	6- 1
Word 2 Charac	teristics continued	
Number of weapon unit assigned with	MBUDDY	60 <b>-</b> 55
Subordinate unit #3	MYMEN(3)	54-49
Subordinate unit #4	MYMEN(4)	48-43
Subordinate unit #5	MYMEN(5)	42-37
Not used		36- 1
Word 3 Charac	teristics continued	
Subordinate unit #6	MYMEN(6)	60-55
Subordinate unit #7	MYMEN(7)	54 <b>-</b> 49
Subordinate unit #8	MYMEN(8)	48-43
Unit can call artillery	LKHQ	42 <b>-</b> 37
Not used		36 <b>-</b> 1
Word 4 Sensor	S	
Sensor #1 height	ISENHL	60 <b>-</b> 55
Sensor #1 class	ISENCL	54 <b>-</b> 52
Sensor #1 type	ISENTL	51 <b>-</b> 49
Sensor #2 height	ISENH2	48-43
Sensor #2 class	ISENC2	42-40
Sensor #2 type	ISENT2	39-37
Not used	1	36- 1
Word 5 Charact	teristics	
Not used		60-49
Enemy units known dead .	JCDEAD	48- 1
Word 6 Charact	teristics	
Not used	. *	60-49
Enemy units detected to nearest square	JCDET	48- 1

<u>JCMD</u>	con	ti	nu	e	
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Description	6400 local 6400 variable bit no
	racteristics
Not used	60-49
Enemy weapon units in LØS	JCLØS 48- 1

## Weapon Basic Data JWEAP (3, 36)

For purposes of data storage the weapons are divided into three groups. These groups are: (1) Artillery and mortars. (2) Direct fire weapons with fragmentation ammo, and (3) Direct fire weapons with no fragmentation ammo. Each weapon requires three words to describe its basic characteristics.

Description			6400 local variable	
Word 1	Basic	Data	var rabre	bit no
Weapon category  1) Arty or mortars  2) DF w/Frag ammo  3) DF w/o Frag ammo			MW PC	60-55
Minimum range  Maximum range  Crew size  Flight time per grid  Rounds/trigger pull  Neutralization weight per round		v <sub>XXX</sub>	MINWRG MAXWRG KREW LFLT LRND1 NW	54-43 42-28 27-22 21-10 9- 4 3- 1

Word 2	Basic Data co	ontinued	11.
Aim time	X <sub>A</sub> XXX		
S. D. Aim time	,	LAIM	60 <b>-</b> 49
Reaim time	∧ <sup>XX</sup>	IAIML	48-43
S. D. Reaim time	$X^VXXX$	LRA IM	42-31
Reload time	$^{V_{XX}}$	LRAIML	30 <b>-</b> 25
retoad cille	X <sub>V</sub> XXX	LØAD	24-13

Description		6400 local variable	6400 bit no.
Word 2	Basic Data continued	variable	OTC NO.
S. D. Reload time Not used	$^{\checkmark}$ XX	I <b>¢</b> ADl	12 <b>-</b> 7 6 <b>-</b> 1
Word 3	Basic Data continued		_
Reload only after impact Range tie breaker Ammo type #1 is fragmentat Ammo type #2 is fragmentat Vulnerability Class #1 use Vulnerability Class #12 use	cion #2  Ammo #2  .	KLI LRTIE MKIL1 MKIL2 LKAM	60 59 58 57 56 •
Category 2-3 weapons Weapons firing signature Category 1 weapons		LKWS	44-39
Direction of artillery impact and width of artillery impact and the Length of artillery impact Not used	area	IMPDIR IMPN1 IMPN2	36-34 33-31 30-28 27- 1

## Total Tactical Standard Deviation JTACSD (12, 28)

Twelve words are required to store the parameters of the hit probability estimator.

Descrip	tion	6400 local variable	6400 bit no
Word 1	Category 2-3 wear	ons	
Total tactical S.D. Ammo #1 $\overline{P}$ , $\overline{M}$	1st round zero range,	, SIGA	60-51
Total tactical S. D. Ammo #1, P, M	lst round .707 max range,	SIGB	50-41
Total tactical_SD. Ammo #1, P. M	1st round max range,	SIGC	40-31
Total tactical S. D. Ammo $\#2$ , $\overline{P}$ , $\overline{M}$	1st round zero range,	SIGA	30-21
Ammo #2, P, M	, 1st round .707 max range,	SIGB	20-11
Total tactical S. D. Ammo #2, P, M	1st round max range,	SIGC	10- 1
Word 2	Category 2-3 weap	ons	
Total tactical S. D. Ammo #1 P, $\overline{M}$	1st round zero range,	SIGA	60-51
Total tactical S. D. Ammo #1, P, $\overline{M}$	1st round .707 max range,	SIGB	50-41
Total tactical S. D. Ammo #1, P, $\overline{M}$	1st round max range,	SIGC	40-31
Total tactical S. D. Ammo #2, P, $\overline{M}$	lst round zero range,	SIGA	30-21
Total tactical S. D. Ammo #2, P, $\overline{M}$	1st round .707 max range,	SIGB	20-11
Total tactical S. D. Ammo #2, P, $\overline{M}$	1st round max range,	SIGC	10- 1
	• •		

Description	6400 local variable	6400 bit no.
Word 12 Category 2-3 weapo	ns	
Total tactical S. D. 2nd round/1st round miss, zero range, Ammo #1 P, M	SIGA	60-51
Total tactical S. D. 2nd round/lst round miss, .707 max range, Ammo #1 P, M	SIGB	
Total tactical S. D. 2nd round/lst round miss, max range, Ammo #1, P, M	SIGC	50 <b>-</b> 41 40 <b>-</b> 31
Total tactical S. D. 2nd round/lst round miss, zero range, Ammo #2 P, M		
Total tactical S. D. 2nd round/ 1st round miss, .707 max range, Ammo #2 P, M	SIGA	30-21
Total tactical S. D. 2nd round/ 1st round miss, max range, Ammo #2 P, M	SIGB	20-11
n 3 K1	SIGC	10- 1

# Kill Probability Non-Fragmentation Ammunition JPKILL (2, 2, 28)

Four words are required to store the kill probabilities of each vulnerability class to each ammo type.

Word 1	Weapon #9	· · · · · · · · · · · · · · · · · · ·	
Kill probability	y vulnerability Class l, Ammo l	LPKH	60-55
Kill probability	y vulnerability Class 2, Ammo 1	LPKH	54-49
Kill probability	vulnerability Class 3, Ammo 1	LPKH	48-43
Kill probability	vulnerability Class 4, Ammo 1	LPKH	42 <b>-</b> 37
Kill probability	vulnerability Class 5, Ammo 1	LPKH	36 <b>-</b> 31
Kill probability	vulnerability Class 6, Ammo 1		
Not used	Allino I	LPKH	30 <b>-</b> 25
			24- 1
Word 2	Weapon #9 continued	*h- <sub>fa</sub>	
****			
Kill probability	vulnerability Class 1, Ammo 2	LPKH	60-55
Kill probability	vulnerability Class 2, Ammo 2	LPKH	54-49
Kill probability	Vulnerability Class 2 A	LPKH	
Kill probability	vulnerability dlags by		48-43
Kill probability	vulnerability Class 5, Ammo 2	LPKH	42-37
Kill probability	varinerability Class 5, Ammo 2	LPKH	36-31
	vulnerability Class 6, Ammo 2	LPKH	30 <b>-</b> 25
Not used			24- 1
			C+= T

Description	6400 local variable	6400 bit no.
Word 3 Weapon #9 continue		DIO 110.
"outpoin "/ conformation	<u>:a</u>	
Kill probability vulnerability Class 7, Ammo 1	LPKH	60 <b>-</b> 55
• • •	•	•
•	•	•
12	,	
Word 4 Weapon #9 continue	<u>-d</u>	
Kill probability vulnerability Class 7, Ammo 2	LPKH	60 <b>-</b> 55
Kill probability vulnerability Class 8, Ammo 2	LPKH	54 <b>-</b> 49
Kill probability vulnerability Class 9, Ammo 2	LPKH	48-43
Kill probability vulnerability Class 10, Ammo 2	LPKH	42-37
Kill probability vulnerability Class 11, Ammo 2	LPKH	36 <b>-</b> 31
Kill probability vulnerability Class 12, Ammo 2	LPKH	30 <b>-</b> 25
Not used		24- 1
•		
•		
Word 112, Weapon 36 continued	_	
wedpoir 30 continue	<u>d</u>	
Kill probability vulnerability Class 7, Ammo 2	LPKH	60 <b>-</b> 55
• • •		
•		
Kill probability vulnerability Class 12, Ammo 2	LPKH	30 <b>-</b> 25
Not used		24- 1
Kill Probability Fragmentation Ammunition JFRAG (2,	.18\	
Two words per weapon are required to store the (given a hit) of infantry by fragmentation weapons.	probability	of kill
Word 1 Weapon 1		
Kill probability, Ammo 1, Net Cover 1 Fire Response 1, 2, or 3	LPKIH	60 55
Kill probability, Ammo 1, Net Cover 2	TILVIU	60-55
Fire Response 1, 2, or 3	LPKIH	54-49

	6400 local variable	6400 bit no.
Word 1 Weapon 1 continued		
Kill probability, Ammo 1, Net Cover 3 Fire Response 1, 2, or 3	LPKIH	48-43
Kill probability, Ammo 1, Net Cover 1 Fire Response 4	LPKTH	42-37
Kill probability, Ammo 1, Net Cover 2 Fire Response 4	, Tbkih	_
Kill probability, Ammo 1, Net Cover 3 Fire Response 4		36-31
Not used	LPKIH	30 <b>-</b> 25 24 <b>-</b> 1
Word 2 Weapon 1 continued		
Kill probability, Ammo 2, Net Cover 1 Fire Response 1, 2, or 3	LPKIH	60 <b>-</b> 55
Kill probability, Ammo 2, Net Cover 2 Fire Response 1, 2, or 3	LPKIH	54 <b>-</b> 49
Kill probability, Ammo 2, Net Cover 3 Fire Response 1, 2, or 3	LPKIH	48-43
Kill probability, Ammo 2, Net Cover 1 Fire Response 4	LPKIH	42-37
Kill probability, Ammo 2, Net Cover 2 Fire Response 4	LPKIH	36 <b>-</b> 31
Kill probability, Ammo 2, Net Cover 3 Fire Response 4	LPKIH	
Not used	111 17111	30 <b>-</b> 25 24 <b>-</b> 1
• •		L, T
• •		
Word 36 Weapon 18 continued		•
Kill probability, Ammo 2, Net Cover 1	LPKIH	60-55
• • • • •		
Kill probability, Ammo 2, Net Cover 3 Not used	LPKIH	30 <b>-</b> 25 24 <b>-</b> 1

## Target Detection Data JDTECT (31, 6, 6)

Thirty-one words are used to store the detection data for each sensor class and sensor type. One word contains the sensor's basic data and two words contain the solid angle thresholds. Twenty-six words contain the probability of detection of dead and nonfiring targets. Two words contain the probability of detecting firing targets.

	6400 local	6400
Mana 3	variable	bit no
Dasie Data		
Scan time $X_{\Lambda}XXXX$	ISCAN	60-46
Minimum sensor range nonfiring targets	MINSRG	45-33
Maximum sensor range nonfiring targets	MAXRG	32-20
Maximum sensor range firing targets	MAXRF	19- 7
Probability of loss of nearest square info target out of line of sight	LTI	6- 1
Word 2 Solid Angle Thresholds Nonfiring T	argets	
Smallest solid angle Gl	LKGTl	60-41
Intermediate solid angle G2	LKGT2	40-21
Largest solid angle G3	LKGT3	20- 1
Word 3 Detection of Dead	_	20- 1
$SA < G1, \overline{M}, \overline{P}$	Tal ge US	
$G1 \leq SA < G2, \overline{M}, \overline{P}$	LPDC	60-55
$G2 \leq SA < G3, \overline{M}, \overline{P}$	LPDC	54-49
$SA \geq G3, \overline{M}, \overline{P}$	LPDC	48 <b>-</b> 43
$SA < G1, \overline{M}, P$	LPDC	42 <b>-</b> 37
$G1 \leq SA < G2, \overline{M}, P$	LPDC	36 <b>-</b> 31
$G2 \leq SA < G3, \overline{M}, P$	LPDC	30 <b>-</b> 25
$SA \geq G3, \overline{M}, P$	LPDC	24-19
Not used	LPDC	18-13
Not used		12- 1
Word 4 Detection of Dead Targets con	tinued	
$SA < G1, M, \overline{P}$	LPDC	60-55
$G1 \leq SA < G2, M, \overline{P}$	LPDC	54-49

Description	6400 local variable	6400 bit no.
Word 4 Detection of	Dead Targets continued	
$G2 \leq SA < G3, M, \overline{P}$	Tangers Continued	
SA ≥ G3, M, <del>P</del>	LPDC	48-43
	LPDC	42-37
SA < G1, M, P	LPDC	36-31
$G1 \leq SA < G2$ , M, P	LPDC	30-25
$G2. \leq SA < G3, M, P$	, TbDC	24-19
$SA \ge G3$ , M, P	LPDC	18-13
Not used		12- 1
Words 5 and 6 Detection Proba	bilities Nonfiring Targets	
See Words 3 and 4 for format		
• •	LP12	
•		
Words 27 and 28 Detection Proba	shilitian N. a	
	Monfiring Targets	
See Words 3 and 4 for format		
Word 29 Solid Angle Threshol	ds Firing Targets	
Smallest solid angle Gl ≥ 3	XX <sub>A</sub> XXXX KSA1	60-41
Intermediate solid angle G2	KSA2	40-21
Largest solid angle G3	KSA3	20- 1
Word 30 Detection Probabilit	•	20- 1
	res filling largets	
SA < G1, P	KDP13	60 <b>-</b> 55
$G1 \leq SA < G2$ , P	KDP13	54 <b>-</b> 49
$G2 \leq SA \leq G3$ , P	KDP13	48-43
SA ≥ G3, P	KDP13	42-37
$SA < G1, \overline{P}$	KDP13	36-31
$G1 \leq SA < G2, \overline{P}$	KDP13	30-25
$G2 \leq SA < G3, \overline{P}$	KDP13	24-19
$SA \geq G3, \overline{P}$	KDP13	18-13
Not used		12- 1

Desc	eription	6400 local variable	6400 bit no.
Word 31	Detection Probabilities Firing T	argets	
SA < Gl, P		KDP34	60-55
$G1 \leq SA < G2, P$		KDP34	54-49
$G2 \leq SA < G3$ , P	·	KDP314	48-43
SA ≥ G3, P		KDP3 <sup>1</sup> 4	42-37
$SA < G1, \overline{P}$		′ KDP34	36-31
$G1 \leq SA < G2, \overline{P}$		KDP34	30 <b>-</b> 25
$G2 \leq SA < G3, \overline{P}$		KDP34	24-19
$SA \ge G3, \overline{P}$		KDP34	18-13
Not used		101 )4	12-1

# Cover and Concealment Conversion JCNVRT (6, 6)

Six words per element size are required to convert the cover and concealment values of the terrain to element radii for hit probability and detection calculations.

Word 1	Concealment Convers	ion	
Apparent radius	(X.X) concealment Index 1	LCØN1	60-55
Apparent radius	(X.X) concealment Index 2	LCØN1	54-49
Apparent radius	(X.X) concealment Index 3	LCØN1	48-43
Apparent radius	(X.X) concealment Index 4	LCØN1	42-37
	(X.X) concealment Index 5	LCØN1	36-31
Apparent radius	(X.X) concealment Index 6	LCØN1	30-25
	(X.X) concealment Index 7	LCØNl	24-19
Apparent radius	(X.X) concealment Index 8	LCØN1	18-13
Not used			12- 1
Word 2	Concealment Conversion continue	ed_	
Apparent radius	(X.X) concealment Index 9	LCØN1	60-55
Apparent radius	(X.X) concealment Index 10	LCØN1	54 <b>-</b> 49
Apparent radius	(X.X) concealment Index 11	LCØN1	48-43
Apparent radius	(X.X) concealment Index 12	LCØNI	42 <b>-</b> 37

Descriptio	n	6400 local variable	6400 bit no.
Word 2	Concealment Conversion contir		
Apparent radius (X.X) Apparent radius (X.X) Apparent radius (X.X) Not used	concealment Index 14	lcønl Lønl	36-31 30-25 24-19 18- 1
Word 3	Cover 1 Conversion		
Apparent radius (X.X)	Cover Index 1	rcøni •	60 <b>-</b> 55
Word 4	Cover 1 Conversion continued	•	•
Apparent radius (X.X)		Lcøvi • •	60-55
Net cover (1, 1, 3) Cov	rer Index 1	Lcøv2 •	60-55
	over 2 Conversion continued		
Net cover (1, 2, 3) Cov	er Index 9  • • • •	LCØV2	60-55

# Ground Mobility Data JGM/B (11, 5)

Eleven words per ground mobility class are required. One word contains the dismount time (mount time in the case of infantry) and the slope thresholds. Ten words are required to give the minimum moving times for the slope classes and trafficability.

Description	6400 local	6400
Word 1 Time and Slope Thresholds	variable	bit no.
Dismount (mount) time	LDMTIM	(0 ha
Slope threshold Ml		60-41
Slope threshold M2	$LSL \not P(1)$	40-31
Slope threshold M3	$LSL \not P(2)$	_
Not used	$ISI\phi P(3)$	
Word 2 Minimum Moving Times (H=1)		10-1
Negligible Slope, ΔE   < ML		
No road, Tl	LMMTG	60-41
No road, T2	LMMTG	40-21
No road, T3	LMMTG *	20- 1
Word 3 Minimum Moving Times (H=1) continued	÷	
Negligible Slope,   AE   < M1		
Road, R1	LMMTG	60-41
Road, R2	LMMT	40-21
Road, R3	LMMIG	20- 1
Word 4 Minimum Moving Times (H=2)		
Moderate downhill slope, -M2 < AE < -M		
See Word 2 for format	LMMTG	
•	•	
•	•	
Word 8 Minimum Moving Times (H=4)		
Moderate uphill slope, $ML < \Delta E < M2$		
See Word 2 for format	•	

Description

6400 local 6400 variable bit no.

## Word 11 Minimum Moving Times (H=5) continued

## Steep uphill slope, M2 < $\Delta$ E < M3

See Word 3 for format

LMMTG

## Air Mobility Data JAMOB (5, 3)

Five words per air mobility class are required. One word contains five of the six altitude changes (in vertical feet per grid square) that an air mobility class can make. Word two contains the sixth altitude change, the attack speed index, and the first two of the five minimum moving times for an altitude change in a slope class. Word three contains the remaining three minimum moving times. Word four contains the standard altitude increment, the maximum altitude, the altitude above ground for contour flight, and the altitude for level flight. Word five contains the vertical descent time, the vertical climb time, and the dismount time.

Description		6400 local variable	6400 bit no.
Word 1 Altitude cha	inge tiresholds		
Steep descent threshold, ft/grid  Moderate descent threshold, ft/grid  Negligible descent threshold, ft/grid  Negligible climb threshold, ft/grid  Moderate climb threshold, ft/grid  Word 2  Miscellaneous Overflow		IACTT (1) IACTT (2) IACTT (3) IACTT (4) IACTT (5)	60-49 48-37 36-25 24-13 12-1
Steep climb threshold, ft/grid Attack speed index Steep descent, ft/grid Moderate descent, ft/grid	3XX <sup>V</sup> XXXX	LACTT (6) KASPD LMMTA (1) LMMTA (2)	60-49 48-43 42-22 21- 1

nued

SHIPE CONTINUE			
Description		6400 local variable	
Word 3 Minimum Mov	ing Tim <b>e</b> s		
Negligible change	3XX XXXXX	LMMTA (3)	60-41
Moderate climb, ft/grid	3XX <sup>V</sup> XXXX	LMMTA (4)	40-21
Steep climb, ft/grid	3XX <sup>V</sup> XXXX	LMMTA (5)	20- 1
Word 4 Altitude and	d Speed	,	
Standard altitude increment		LDELAS	60-46
Maximum altitude		KHI	45-31
Altitude above ground (contour)		LITA	30-16
Altitude level flight		LARGA	15- 1
Word 5 Special Time	<u>es</u> , ,		
Vertical descent time	3XX <sup>x</sup> XXXX	INCIDN	60-40
Vertical climb time	3XX <sup>X</sup> XXXX	INCTUP	39 <b>-</b> 19
Dismount time	3XX,XXXX	KDMTIM	18- 1

### Visual Devices JVISA (6, 2)

Six words are used to store the common logarithm of the critical visual angle for 31 values of log target-background contrast (-1.50 to 0.00) in increments of .05 for each of two devices for the given light level of the treatment. Device #1 is unaided; device #2 is 7x50 binoculars.

Unaided Eye

Description		6400 bit no.
Word 1		
Log angle for log contrast	<b>-1.</b> 50	60-52
Log angle for log contrast	-1.45	51-43
Log angle for log contrast	-1.40	42-34
Log angle for log contrast	<b>-1.3</b> 5	33 <b>-</b> 25
Log angle for log contrast	-1.30	24-16
Log angle for log contrast	-1.25	15- 7
Not used		6- 1

Description		6400 bit no
Word 2		
Log angle for log contrast	-1.20	60-52
log angle for log contrast	-1.15	51 <b>-</b> 43
Log angle for log contrast	-1.10	. 42-34
Log angle for log contrast	-1.05	33 <b>-</b> 25
Log angle for log contrast	-1.00	24-16
Log angle for log contrast	<b></b> 95	15- 7
Not used		6- 1
Word 3		
•		
• *		
Word 4		
•		
• •		
Word 5		
Log angle for log contrast	-0.30	60-52
Log angle for log contrast	-0.25	51-43
log angle for log contrast	-0.20	42-34
log angle for log contrast	-0.15	33 <b>-2</b> 5
Log angle for log contrast	-0.10	24-16
Log angle for log contrast	-0.05	15- 7
Not used		6- 1
Word 6		
Log angle for log contrast	0.00	60 <b>-</b> 52
Not used		51- 1

## Minimum Target Dimension JDIM (3)

Three words are used to store the minimum target dimension for the 16 target classes.

Description	6400 Bit no.
Word 1	
Minimum target dimension Target Class 1 XX	6 <b>0-</b> 52
Minimum target dimension Target Class 2 XXXX	, 51 <b>-</b> 43
Minimum target dimension Target Class 3 XX <sub>A</sub> X	42-34
Minimum target dimension Target Class 4 XX,X	33 <b>-</b> 25
Minimum target dimension Target Class 5 XXXX	24-16
Minimum target dimension Target Class 6 XXAX	15- 7
Not used	6- 1
Word 2	
Minimum target dimension Target Class 7	60 <b>-</b> 52
Minimum target dimension Target Class 8	51-43
Minimum target dimension Target Class 9	42-34
Minimum target dimension Target Class 10	33-25
Minimum target dimension Target Class 11	24-16
Minimum target dimension Target Class 12	15- 7
Not used	6- 1
Word 3	
Minimum target dimension Target Class 13	60 <b>-</b> 52
Minimum target dimension Target Class 14	51-43
Minimum target dimension Target Class 15	42-34
Minimum target dimension Target Class 16	33-25
Not used	24- 1

(Note: In unpacking, retrieve 9 bits and divide by 10.0)

#### Computational Values (Real)

Image intensifier constant Kl CKl (6). Six words are used to store the computed value of Kl =  $t \times Tau \times PI/4$ . DFNO for the 6 image intensifier devices. These are real numbers.

Image intensifier constant K2 CK2 (6). Six words are used to store the computed value of K2 =  $4 \times PI$  (resolution length)<sup>2</sup> for the 6 image intensifier devices. Each value for each device is stored as a real number.

Modulation transfer function EDMTF (6). Six words are used to store the modulation transfer function for the 6 image intensifier devices. Each integral approximation for each device is stored as a real number.

<u>Image intensifier Value P2, P2 (6)</u>. Six words are used to store the value computed integral approximation P2 for the 6 image intensifier devices. Each value for each device is stored as a real number.

Background reflectance of the grid square for I.I. devices BREFML (6, 16). Sixteen words are used to store the background reflectance for I. I. devices for 16 background numbers of the grid squares for each of the 6 image intensifier devices. Each value for each device and each background number is stored as a real number.

Target reflectance for I. I. Devices TREFM2 (6, 16). Sixteen words are used to store the target reflectance for I. I. devices for 16 target classes for each of 6 image intensifier devices. Each value for each device and each target class is stored as a real number.

Integral of relative luminosity and night sky brightness Pl (3). Three words are used to store the computed integral approximation of night sky brightness and relative luminosity Pl for the three light levels of: l=starlight; 2=moonlight, and 3=part moon. Each value for each light level is stored as a real number.

Background reflectance of the grid square for visual devices

BREFM3 (16). Sixteen words are used to store the computed approximation of background reflectance of the grid square for visual devices

for the 16 background numbers. Each value for each background number is stored as a real number.

Target reflectance for visual devices TREFM4 (16). Sixteen words are used to store the computed approximation of target reflectance for visual devices for 16 target classes. Each value for each target class is stored as a real number.

### Night Sky Brightness SBK (11)

Eleven words are used to store the data of night sky brightness for the specific light level as defined in the treatment as 1 = starlight; 2 = moonlight, and 3 = partial moonlight. The measure of light level is in foot-lamberts.

#### Word 1

Light level for wavelength (microns) = .40

#### Word 2

Light level for wavelength (microns) = .45

#### Word 3

Light level for wavelength (microns) = .50

### Word 4

Light level for wavelength (microns) = .55

#### Word 5

Light level for wavelength (microns) = .60

#### Word 6

Light level for wavelength (microns) = .65

#### Word 7

Light level for wavelength (microns) = .70

#### Word 8

Light level for wavelength (microns) = .75

SBK continued

#### Word 9

Light level for wavelength (microns) = .80

#### Word 10

Light level for wavelength (microns) = .85

#### Word 11

Light level for wavelength (microns) = .90

## Radar Characteristics JRADAR (6)

One word is used to store the radar characteristics for each of six radars.

Description	6400 local variable	6400 bit no.
Maximum range personnel  Maximum range vehicles	MRPER MRVEH	60-46 45-28
Threshold velocity of target	MRVEL	27 <b>-</b> 13
Not used		12- 1

## Run Control Data JRUN (14)

Fourteen words contain the run control of	data.	6400 Word No.
Maximum battle time	KMAX	1
Maximum number of replications	NR	2
Initial random number	KN	3
Treatment data to be used	NT	4
X Coordinate for proximity termination	ΚX	5
Y Coordinate for proximity termination	KY	6
Distance for proximity termination	KDIS	7
Side for proximity termination	KSIDE	8
Number of units for proximity termination	KUNITS	9
Red fraction of casualties for termination	KREDFC	10
Blue fraction of casualties for termination	KBLUFC	11
Not used		12

#### JRUN continued

Description	6400 local variable	
Last random number	KSTRN	13
Current replication number	NRP	14

### IARTY (6, 15, 2) and IHEL(6, 15, 2)

Six targets against which each command unit for each side can call artillery or helicopter support.

### Special Data JDATA (17)

This is a collection of data required to run the battle model more efficiently or to be used for debug runs on the battle model.

Daniel de la constant	6400 local	
Description	variable	word no.
Value of lower infinity* 377 77708	INFL	1
Value of upper infinity** 377 7777 8	INFU	2
Decision cycle	KCTIME	3
Assessment Interval	KATIME	4
Neutralization Interval	INTN	5
Not used	INTU	6
Neutralization clock	ICLKN	7
Not used	ICLKU	8
Control switch for using ABUG	NSW CH	9
Time to begin printing ABUG	NOW	10
Time to stop printing ABUG	LATER	11 .
Not used		12
Not used		13
Not used		14
Not used		15
Not used		16
Not used		17

<sup>\*</sup>INFL = 1048568 10 \*\*INFU = 1048575 10

### Conditions JCØND

One word is used to store the visible light attenuation coefficients of scattering and absorption and the radar degradation factor.

Description	Local variable	Bit no.
Scattering coefficient	X <sub>A</sub> XXXXXXX SIGS (times 10 <sup>7</sup> )	60-37
Absorption coefficient	XXX <sub>A</sub> XXXXX SIGA (times 10 <sup>5</sup> )	36 <b>-</b> 1.3
Radar degradation factor	$X_{\Lambda}X_{\Lambda}$	12- 1

## Visual Device Magnification JDMAG

One word is used to store the magnification of six visual devices and the light level condition.

Magnification of Device 1	XX,XX	DMAG(1)	60 <b>-</b> 52
Mamaidiantian at Davis o	777 47		1 -
Magnification of Device 2	$XX^{V}X$	DMAG(2)	51 <b>-</b> 43
Magnification of Device 3	vvv	DM(0/2)	ادم ماد
ragiliticación of Device 3	$XX^{v}X$	DMAG(3)	42 <b>-</b> 34
Magnification of Device 4	vv v	DMAG(4)	22.05
ragilitication of Device 4	$XX^{\vee}X$	DMAG(4)	33 <b>-</b> 25
Magnification of Device 5	$XX_{\bullet}X$	DMAG(5)	24-16
implification of pevice )	$\mathbf{v}^{\mathbf{v}}$	DMAG(5)	24 <b>-</b> 10
Magnification of Device 6	$XX_{\mathbf{A}}X$	DMAG(6)	15- 7
implification of Device o	$\Lambda \Lambda \Lambda \Lambda$	DIMAG(O)	エノー (
Light level condition (1, 2,	or 3)	KOND	6- 1
			0- 1
(l= starlight; 2 = moonli	gnt; 3 = part moon)		

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☐ E14	Comptroller	1
[∑] E15	The Army Library, Attn: ASDIRS	1
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₩ E23	Assistant Chief of Staff for Force Development	10
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E32	Office of Reserve Components	4
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	UNIFIED COMMANDS	1
□ L5	Commander in Chief, Alaska (CINCAL)	1
☐ <u>L</u> 6	Commander in Chief, Pacific (CINCPAC)	1
☐ L12	Commander in Chief, Europe (CINCEUCOM)	•
☐ L16	US Strike Command, MacDill Air Force Base (CINCSTRIKE)	
	ARMY COMMANDS (CONUS)	
<u> </u>	US Army Security Agency US Army Air Defense Command	
□ L61	US Continental Army Command	
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(T) 10	US Army, Alaska	
☐ L8 ☐ L9	US Army Forces Southern Command	
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<sup>\*</sup> Required IAW AR 70-11 and AR 70-31.

<sup>\*\*</sup> Normally required; exclusion must be justified by Sponsor (AR 1-28).

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